

Variation of Parameters

Nonhomog. Lin. System (*)
in n -dim.

$$\frac{d\vec{x}}{dt} = A(t)\vec{x} + \vec{f}(t)$$

Step 1 Prepare complementary solutions & a fundamental matrix $M(t)$.
i.e. Solve the homog. system $\vec{x}'_c = A(t)\vec{x}_c$

Step 2. Variation of Parameters. Set $\vec{x}(t) = M(t)\vec{u}(t)$.

$$\text{The equation } (*) \Leftrightarrow \frac{d\vec{u}}{dt} = M(t)^{-1}\vec{f}(t) \quad (**)$$

• Integrate to get $\vec{u}_p(t)$: a particular sol of (**).

• Then $\vec{x}_p(t) = M(t)\vec{u}_p(t)$ is a particular sol of (*)

Finally, the general solutions of (*) are $\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t)$.

Example 1 Solve $\vec{x}' = A\vec{x} + \vec{f}(t)$, where $A = \begin{bmatrix} -9 & -8 & 3 \\ 8 & 7 & -3 \\ -6 & -6 & 2 \end{bmatrix}$, $\vec{f}(t) = \begin{bmatrix} \frac{1-3t}{1+t} e^t + (2-2t)e^t \\ \frac{3t}{1+t} e^{-t} + (-1+2t)e^t \\ \frac{2}{1+t} e^{-t} + 3e^t \end{bmatrix}$

Solution $\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t)$.

Step 1 Find $\vec{x}_c(t)$: Complementary sols. i.e. sols of $\vec{x}'_c = A\vec{x}_c$.

• Eigenvalues of A : $\det(A - \lambda I) = \dots = -\lambda^3 + 3\lambda + 2 = (\lambda - 2)(\lambda + 1)^2 \Rightarrow \lambda_1 = 2, \lambda_2 = \lambda_3 = -1$.

• Eigenvectors for $\lambda_1 = 2$:

$$(A - 2I)\vec{x} = \vec{0} \Leftrightarrow \begin{bmatrix} -11 & -8 & 3 \\ 8 & 5 & -3 \\ -6 & -6 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

• Generalized Eigenvectors for $\lambda_2 = \lambda_3 = -1$

$$(A + I)^2 \vec{x} = \vec{0} \Leftrightarrow \begin{bmatrix} -18 & -18 & 9 \\ 18 & 18 & -9 \\ -18 & -18 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow x_1 + x_2 - \frac{1}{2}x_3 = 0$$

$$\Leftrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 + \frac{1}{2}x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} \frac{1}{2} \\ 0 \\ 1 \end{bmatrix}.$$

• Complementary sols.

$$\begin{aligned} \vec{x}_c(t) &= c_1 e^{2t} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{t} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-t} \begin{bmatrix} \frac{1}{2} \\ 0 \\ 1 \end{bmatrix} = c_1 e^{2t} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{-t} \{I + t(A + I)\} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-t} \{I + t(A + I)\} \begin{bmatrix} \frac{1}{2} \\ 0 \\ 1 \end{bmatrix} \\ &= c_1 e^{2t} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{-t} \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + t \begin{bmatrix} -8 & -8 & 3 \\ 8 & 8 & -3 \\ -6 & -6 & 3 \end{bmatrix} \right\} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-t} \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + t \begin{bmatrix} -8 & -8 & 3 \\ 8 & 8 & -3 \\ -6 & -6 & 3 \end{bmatrix} \right\} \begin{bmatrix} \frac{1}{2} \\ 0 \\ 1 \end{bmatrix} \\ &= c_1 e^{2t} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-t} \begin{bmatrix} \frac{1}{2} \\ 0 \\ 1 \end{bmatrix}. \end{aligned}$$

Step 2. Variation of Parameters

A fundamental matrix $M(t) = \begin{bmatrix} 2t & -e^{-t} & (\frac{1}{2}-t)e^{-t} \\ -e^{2t} & e^{-t} & te^{-t} \\ e^{2t} & 0 & e^{-t} \end{bmatrix}$.

Set $\vec{x}(t) = M(t) \vec{u}(t)$. The eq for $\vec{u}(t)$ is:

$$\vec{u}'(t) = M(t)^{-1} \vec{f}(t) = \begin{bmatrix} -2e^{-2t} & -2e^{-2t} & e^{-2t} \\ (-2-2t)e^t & (-1-2t)e^t & e^t \\ 2e^t & 2e^t & 0 \end{bmatrix} \begin{bmatrix} \frac{1-3t}{1+t} e^t + (2-2t)e^t \\ \frac{3t}{1+t} e^{-t} + (-1+2t)e^t \\ \frac{2}{1+t} e^{-t} + 3e^t \end{bmatrix}$$

$$\vec{u}'(t) = \begin{bmatrix} e^{-t} \\ \frac{t}{1+t} \\ \frac{2}{1+t} + 2e^{2t} \end{bmatrix} \quad \xrightarrow{\text{integrate}} \quad \vec{u}_p(t) = \begin{bmatrix} -e^{-t} \\ t - \ln|1+t| \\ 2\ln|1+t| + e^{2t} \end{bmatrix}$$

$$\begin{aligned} \vec{x}_p(t) &= M(t) \vec{u}_p(t) = \begin{bmatrix} e^{2t} & -e^{-t} & (\frac{1}{2}-t)e^{-t} \\ -e^{2t} & e^{-t} & te^{-t} \\ e^{2t} & 0 & e^{-t} \end{bmatrix} \begin{bmatrix} -e^{-t} \\ t - \ln|1+t| \\ 2\ln|1+t| + e^{2t} \end{bmatrix} \\ &= \begin{bmatrix} e^t(-\frac{1}{2}-t) + e^{-t}(-t + 2\ln|1+t| - 2t\ln|1+t|) \\ e^t(1+t) + e^{-t}(t - \ln|1+t| + 2t\ln|1+t|) \\ 2e^{-t}\ln|1+t| \end{bmatrix}. \end{aligned}$$

Gen. Sol's of $\vec{x}' = A\vec{x} + \vec{f}(t)$

$$\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t) = \dots + \dots$$

Example 2 Solve $4y''' + 9y' = \sec \frac{3t}{2}$ (*)

Solution $y(t) = y_p(t) + y_c(t)$

Step 1 Find $y_c(t)$: $4y_c''' + 9y_c' = 0$

- Eigenvalues: $4\lambda^3 + 9\lambda = \lambda(4\lambda^2 + 9) \Rightarrow \lambda_1 = 0, \lambda_2 = \frac{3}{2}i, \lambda_3 = -\frac{3}{2}i$

- $y_c(t) = C_1 + C_2 \cos \frac{3t}{2} + C_3 \sin \frac{3t}{2}$

Step 2 Convert (*) to a nonhomogeneous linear system:

- Define $\vec{x}(t) = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y \\ y' \\ y'' \end{bmatrix}$. The eq's for \vec{x} :

$$\begin{cases} x_1' = y' = x_2 \\ x_2' = y'' = x_3 \\ x_3' = y''' = -\frac{9}{4}y + \frac{1}{4}\sec \frac{3t}{2} = -\frac{9}{4}x_2 + \frac{1}{4}\sec \frac{3t}{2} \end{cases}$$

$$\vec{x}' = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -\frac{9}{4} & 0 \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ 0 \\ \frac{1}{4}\sec \frac{3t}{2} \end{bmatrix} \quad \text{Pay attention to the Coeff. } \frac{1}{4}$$

- Complementary Solutions of the system: $\vec{x}_c(t) = C_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} \cos \frac{3t}{2} \\ -\frac{3}{2} \sin \frac{3t}{2} \\ -\frac{9}{4} \cos \frac{3t}{2} \end{bmatrix} + C_3 \begin{bmatrix} \sin \frac{3t}{2} \\ \frac{3}{2} \cos \frac{3t}{2} \\ -\frac{9}{4} \sin \frac{3t}{2} \end{bmatrix}$

- A fundamental matrix:

$$M(t) = \begin{bmatrix} 1 & \cos \frac{3t}{2} & \sin \frac{3t}{2} \\ 0 & -\frac{3}{2} \sin \frac{3t}{2} & \frac{3}{2} \cos \frac{3t}{2} \\ 0 & -\frac{9}{4} \cos \frac{3t}{2} & -\frac{9}{4} \sin \frac{3t}{2} \end{bmatrix}$$

Step 3. Variation of Parameters

Set $\vec{x}(t) = M(t) \vec{u}(t)$.

The Diff. Eq. for $\vec{u}(t)$ becomes:

$$\vec{u}'(t) = M(t)^{-1} \vec{f}(t) = \begin{bmatrix} 1 & 0 & \frac{4}{9} \\ 0 & -\frac{2}{3} \sin \frac{3t}{2} & -\frac{4}{9} \cos \frac{3t}{2} \\ 0 & \frac{2}{3} \cos \frac{3t}{2} & -\frac{4}{9} \sin \frac{3t}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \frac{1}{4} \sec \frac{3t}{2} \end{bmatrix} = \begin{bmatrix} \frac{1}{9} \sec \frac{3t}{2} \\ -\frac{1}{9} \\ -\frac{1}{9} \tan \frac{3t}{2} \end{bmatrix}$$

Integrate

$$\vec{u}_p(t) = \begin{bmatrix} \frac{2}{27} \ln \left| \sec \frac{3t}{2} + \tan \frac{3t}{2} \right| \\ -\frac{1}{9} t \\ \frac{2}{27} \ln \left| \cos \frac{3t}{2} \right| \end{bmatrix}$$

$$\Rightarrow \vec{x}_p(t) = M(t) \vec{u}_p(t)$$

$$\Rightarrow y_p(t) = [\text{the first component of } \vec{x}_p(t)]$$

$$\begin{aligned} &= (\text{the first component of } \begin{bmatrix} 1 & \cos \frac{3t}{2} & \sin \frac{3t}{2} \\ * & * & * \\ * & * & * \end{bmatrix} \begin{bmatrix} \frac{2}{27} \ln \left| \sec \frac{3t}{2} + \tan \frac{3t}{2} \right| \\ -\frac{1}{9} t \\ \frac{2}{27} \ln \left| \cos \frac{3t}{2} \right| \end{bmatrix}) \\ &= \frac{2}{27} \ln \left| \sec \frac{3t}{2} + \tan \frac{3t}{2} \right| - \frac{1}{9} t \cos \frac{3t}{2} + \frac{2}{27} \sin \frac{3t}{2} \ln \left| \cos \frac{3t}{2} \right|. \end{aligned}$$

Gen. Sol's of $4y''' + 9y' = \sec \frac{3t}{2}$ are:

$$y(t) = y_p(t) + y_c(t) = \frac{2}{27} \ln \left| \sec \frac{3t}{2} + \tan \frac{3t}{2} \right| - \frac{1}{9} t \cos \frac{3t}{2} + \frac{2}{27} \sin \frac{3t}{2} \ln \left| \cos \frac{3t}{2} \right| + C_1 + C_2 \cos \frac{3t}{2} + C_3 \sin \frac{3t}{2}$$