

Variation of Parameters for n -Dim. Nonhomog. Linear Systems

$$(*) \quad \frac{d\vec{x}}{dt} = A(t)\vec{x} + \vec{f}(t)$$

Step 1. Prepare complementary solutions $\vec{x}_c(t)$ & a fundamental matrix $M(t)$.

i.e. Solve the homog. system $\frac{d\vec{x}_c}{dt} = A(t)\vec{x}_c$ to get

$$\vec{x}_c(t) = C_1 \vec{x}_1(t) + C_2 \vec{x}_2(t) + \dots + C_n \vec{x}_n(t). \quad \leftarrow \text{complementary sols.}$$

Let $M(t) = [\vec{x}_1(t) \quad \vec{x}_2(t) \quad \dots \quad \vec{x}_n(t)]$. (an $n \times n$ invertible matrix)

\nwarrow a fundamental matrix.

Step 2. Variation of Parameters.

Set $\vec{x}(t) = M(t) \vec{u}(t)$.

The Equation (*) $\Leftrightarrow \frac{d\vec{u}}{dt} = M(t)^{-1} \vec{f}(t)$ (***)

Step 3. Integrate to get $\vec{u}_p(t)$: a particular solution of (***)

Step 4. Then $\vec{x}_p(t) = M(t) \vec{u}_p(t)$ is a particular solution of (*),

and the general solutions of (*) are $\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t)$.

Variation of Parameters works, because of the following equivalence:

Set $\vec{x}(t) = M(t) \vec{u}(t)$.

$$(*) \quad \frac{d\vec{x}}{dt} = A(t) \vec{x}(t) + \vec{f}(t)$$

$$(\ast\ast) \quad \frac{d\vec{u}}{dt} = M(t)^{-1} \vec{f}(t)$$

• Derivation of this Equivalence :

• By definition, $M(t) = [\vec{x}_1(t) \quad \vec{x}_2(t) \quad \dots \quad \vec{x}_n(t)]$,
where $\vec{x}_1(t), \dots, \vec{x}_n(t)$ are linearly indep. Sols of the homog. system:

$$\frac{d\vec{x}_1(t)}{dt} = A(t) \vec{x}_1(t), \quad \dots, \quad \frac{d\vec{x}_n(t)}{dt} = A(t) \vec{x}_n(t).$$

$$\bullet \frac{dM(t)}{dt} = A(t)M(t)$$

Reason: $\frac{dM(t)}{dt} = \left[\frac{d\vec{x}_1(t)}{dt} \quad \frac{d\vec{x}_2(t)}{dt} \quad \dots \quad \frac{d\vec{x}_n(t)}{dt} \right]$

$$= [A(t)\vec{x}_1(t) \quad A(t)\vec{x}_2(t) \quad \dots \quad A(t)\vec{x}_n(t)] =$$

$$= A(t) [\vec{x}_1(t) \quad \vec{x}_2(t) \quad \dots \quad \vec{x}_n(t)] = A(t)M(t)$$

• Substitute $\vec{x}(t) = M(t) \vec{u}(t)$ in $(*)$:

$$\frac{d}{dt} \{ M(t) \vec{u}(t) \} = A(t)M(t) \vec{u}(t) + \vec{f}(t)$$

$$= \underbrace{\frac{dM(t)}{dt} \vec{u}(t)}_{\text{~~~~~}} + M(t) \frac{d\vec{u}}{dt} = A(t)M(t) \vec{u}(t) + M(t) \frac{d\vec{u}}{dt}$$

$$\Leftrightarrow M(t) \frac{d\vec{u}}{dt} = \vec{f}(t)$$

$\Leftrightarrow (\ast\ast)$

Example 1: Solve $\vec{x}' = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \vec{x} + \begin{bmatrix} -1 + 21t + e^{3t} \tan t \\ 2 + 30t + 2e^{3t} \tan t \end{bmatrix}$

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- Eigenvalues & eigenvectors of $\begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix}$ (details skipped here)

$$\Rightarrow \text{Complementary solutions: } \vec{x}_c(t) = C_1 e^{-t} \begin{bmatrix} -1 \\ 2 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

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- Set $\vec{x}(t) = M(t)\vec{u}(t)$
- The original system is simplified to $\vec{u}'(t) = M(t)^{-1} \vec{f}(t)$:

$$\begin{aligned}\vec{u}'(t) &= \begin{bmatrix} -e^{-t} & e^{3t} \\ 2e^{-t} & 2e^{3t} \end{bmatrix}^{-1} \begin{bmatrix} -1 + 21t + e^{3t} \tan t \\ 2 + 30t + 2e^{3t} \tan t \end{bmatrix} \\ &= \frac{1}{-4e^{2t}} \begin{bmatrix} 2e^{3t} & -e^{3t} \\ -2e^{-t} & -e^{-t} \end{bmatrix} \begin{bmatrix} -1 + 21t + e^{3t} \tan t \\ 2 + 30t + 2e^{3t} \tan t \end{bmatrix} \\ &= \begin{bmatrix} (1 - 3t)e^t \\ 18te^{-3t} + \tan t \end{bmatrix}.\end{aligned}$$

Example 1 (continued): $\vec{x}' = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \vec{x} + \begin{bmatrix} -1 + 21t + e^{3t} \tan t \\ 2 + 30t + 2e^{3t} \tan t \end{bmatrix}$

► Integrate $\vec{u}'(t) = \begin{bmatrix} (1-3t)e^t \\ 18te^{-3t} + \tan t \end{bmatrix}$:

$$\begin{aligned}\int (1-3t)e^t dt &= (1-3t)e^t - \int (-3)e^t dt = (1-3t)e^t + 3e^t + C, \\ \int 18te^{-3t} dt &= -6te^{-3t} - \int (-6)e^{-3t} dt = -6te^{-3t} - 2e^{-3t} + C, \\ \int \tan t dt &= -\ln |\cos t| + C.\end{aligned}$$

$$\Rightarrow \vec{u}(t) = \begin{bmatrix} (4-3t)e^t + C_1 \\ (-2-6t)e^{-3t} - \ln |\cos t| + C_2 \end{bmatrix}.$$

Example 1 (continued): $\vec{x}' = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \vec{x} + \begin{bmatrix} -1 + 21t + e^{3t} \tan t \\ 2 + 30t + 2e^{3t} \tan t \end{bmatrix}$

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- Finally, the solutions $\vec{x}(t)$ are obtained from $\vec{x}(t) = M(t)\vec{u}(t)$:

$$\begin{aligned}\vec{x}(t) &= \begin{bmatrix} -e^{-t} & e^{3t} \\ 2e^{-t} & 2e^{3t} \end{bmatrix} \begin{bmatrix} (4-3t)e^t + C_1 \\ (-2-6t)e^{-3t} - \ln |\cos t| + C_2 \end{bmatrix} \\ &= \begin{bmatrix} -6-3t-e^{3t}\ln|\cos t| \\ 4-18t-2e^{3t}\ln|\cos t| \end{bmatrix} + C_1 e^{-t} \begin{bmatrix} -1 \\ 2 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}.\end{aligned}$$

Example Solve ~~(*)~~ $\frac{d\vec{x}}{dt} = \begin{bmatrix} -1 - \cos(2t) & -1 - \sin(2t) \\ 1 - \sin(2t) & -1 + \cos(2t) \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ e^{-2t} \end{bmatrix}$,

given the complementary solutions $\vec{x}_c(t) = C_1 e^{-2t} \begin{bmatrix} \cos t \\ \sin t \end{bmatrix} + C_2 \begin{bmatrix} -\sin t \\ \cos t \end{bmatrix}$.

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Solution. The given $\vec{x}_c(t) \Rightarrow$ a Fundamental Matrix $M(t) = \begin{bmatrix} \quad & \quad \\ \quad & \quad \end{bmatrix}$

• Set $\vec{x}(t) = M(t) \vec{u}(t)$. Eq (*) becomes :

$$\frac{d\vec{u}}{dt} = M(t)^{-1} \vec{f}(t)$$

• Integrate $\Rightarrow \vec{u}_p(t) =$ [a particular sol of (**)]

• $\Rightarrow \vec{x}_p(t) = M(t) \vec{u}_p(t) =$ [a particular sol. of (*)]

• General Sol's of (*) :

$$\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t) =$$

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• Integrate $\Rightarrow \vec{u}_p(t) = \begin{bmatrix} -\cos t \\ -\frac{2}{5} e^{-2t} \cos t + \frac{1}{5} e^{-2t} \sin t \end{bmatrix}$ [a particular sol of (*)]

$$\begin{aligned} \cdot \Rightarrow \vec{x}_p(t) &= M(t) \vec{u}_p(t) = \begin{bmatrix} e^{-2t} \cos t & -\sin t \\ e^{-2t} \sin t & \cos t \end{bmatrix} \begin{bmatrix} -\cos t \\ -\frac{2}{5} e^{-2t} \cos t + \frac{1}{5} e^{-2t} \sin t \end{bmatrix} \\ &= e^{-2t} \begin{bmatrix} -\cos^2 t + \frac{2}{5} \cos t \sin t - \frac{1}{5} \sin^2 t \\ -\frac{2}{5} \cos^2 t - \frac{4}{5} \cos t \sin t \end{bmatrix} \quad [\text{a particular sol. of (*)}] \end{aligned}$$

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Example Solve $\frac{d\vec{x}}{dt} = \begin{bmatrix} -1 - \cos(2t) & -1 - \sin(2t) \\ 1 - \sin(2t) & -1 + \cos(2t) \end{bmatrix} \vec{x} + \begin{bmatrix} 0 \\ e^{-2t} \end{bmatrix}$,

given the complementary solutions $\vec{x}_c(t) = C_1 e^{-2t} \begin{bmatrix} \cos t \\ \sin t \end{bmatrix} + C_2 \begin{bmatrix} -\sin t \\ \cos t \end{bmatrix}$.

Solution. The given $\vec{x}_c(t) \Rightarrow$ a Fundamental Matrix $M(t) = \begin{bmatrix} e^{-2t} \cos t & -\sin t \\ e^{-2t} \sin t & \cos t \end{bmatrix}$

• Set $\vec{x}(t) = M(t) \vec{u}(t)$. Eq (*) becomes:

$$\frac{d\vec{u}}{dt} = M(t)^{-1} \vec{f}(t) = \begin{bmatrix} e^{2t} \cos t & e^{2t} \sin t \\ -\sin t & \cos t \end{bmatrix} \begin{bmatrix} 0 \\ e^{-2t} \end{bmatrix} = \begin{bmatrix} \sin t \\ e^{-2t} \cos t \end{bmatrix}.$$

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• General Sol's of (*):

$$\vec{x}(t) = \vec{x}_p(t) + \vec{x}_c(t) = e^{-2t} \begin{bmatrix} -\cos^2 t + \frac{2}{5} \cos t \sin t - \frac{1}{5} \sin^2 t \\ -\frac{2}{5} \cos^2 t - \frac{4}{5} \cos t \sin t \end{bmatrix} + C_1 e^{-2t} \begin{bmatrix} \cos t \\ \sin t \end{bmatrix} + C_2 \begin{bmatrix} -\sin t \\ \cos t \end{bmatrix}.$$

Variation of Parameters for n -th Order Nonhomog. Lin. Diff Eqs.

$$(*) \quad a_n(t) \frac{d^n y}{dt^n} + a_{n-1}(t) \frac{d^{n-1} y}{dt^{n-1}} + \dots + a_1(t) \frac{dy}{dt} + a_0(t)y = f(t).$$

Step 1. Prepare complementary solutions $y_c(t)$ & a fundamental matrix $M(t)$.

i.e. Solve the homog. eq. $a_n(t) \frac{d^n y_c}{dt^n} + a_{n-1}(t) \frac{d^{n-1} y_c}{dt^{n-1}} + \dots + a_1(t) \frac{dy_c}{dt} + a_0(t)y_c = 0$,

to get $y_c(t) = c_1 y_1(t) + \dots + c_n y_n(t)$. \leftarrow Complementary solutions

Let $M(t) = \begin{bmatrix} y_1 & y_2 & \cdots & y_n \\ y'_1 & y'_2 & \cdots & y'_n \\ y''_1 & y''_2 & \cdots & y''_n \\ \vdots & \vdots & & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{bmatrix}$

\leftarrow the Wronskian of y_1, y_2, \dots, y_n
gives a fund. matrix $M(t)$.

Step 2. Set $\vec{x}(t) = \begin{bmatrix} y \\ y' \\ \vdots \\ y^{(n-1)} \end{bmatrix} = M(t) \vec{u}(t)$.

Eq (*) $\iff \frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ f(t)/a_n(t) \end{bmatrix}$

Note that it
is divided by
 $a_n(t)$.

Step 3. Integrate to get $\vec{u}(t)$.

Step 4. $y(t) = y_1(t)u_1(t) + y_2(t)u_2(t) + \dots + y_n(t)u_n(t)$.

Example 2: Solve $2y'' - y' - y = \frac{3e^{\frac{3}{2}t}}{1 + e^t}$.

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- ▶ Eigenvalues: $2\lambda^2 - \lambda - 1 = (2\lambda + 1)(\lambda - 1) \Rightarrow \lambda_1 = -1/2, \lambda_2 = 1$
⇒ Complementary solutions: $y_c(t) = C_1 e^{-\frac{1}{2}t} + C_2 e^t$ with
 $y_1(t) = e^{-\frac{1}{2}t}, y_2(t) = e^t$.

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 $y_1(t) = e^{-\frac{1}{2}t}, y_2(t) = e^t$.
- ▶ A fundamental matrix (the Wronskian of y_1, y_2):

$$M(t) = \begin{bmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{bmatrix} = \begin{bmatrix} e^{-\frac{1}{2}t} & e^t \\ -\frac{1}{2}e^{-\frac{1}{2}t} & e^t \end{bmatrix}.$$

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- ▶ Set $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y \\ y' \end{bmatrix} = M(t)\vec{u}(t)$. The Diff Eq for $\vec{u}(t)$ is:

$$\frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ f(t)/a_2 \end{bmatrix}$$

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$$\begin{aligned} \frac{d\vec{u}}{dt} &= M(t)^{-1} \begin{bmatrix} 0 \\ f(t)/a_2 \end{bmatrix} = \begin{bmatrix} e^{-\frac{1}{2}t} & e^t \\ -\frac{1}{2}e^{-\frac{1}{2}t} & e^t \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ \frac{3e^{\frac{3}{2}t}}{2(1+e^t)} \end{bmatrix} \\ &= \frac{1}{\frac{3}{2}e^{\frac{1}{2}t}} \begin{bmatrix} e^t & -e^t \\ \frac{1}{2}e^{-\frac{1}{2}t} & e^{-\frac{1}{2}t} \end{bmatrix} \begin{bmatrix} 0 \\ \frac{3e^{\frac{3}{2}t}}{2(1+e^t)} \end{bmatrix} = \begin{bmatrix} -\frac{e^{2t}}{1+e^t} \\ \frac{e^{\frac{1}{2}t}}{1+e^t} \end{bmatrix}. \end{aligned}$$

Example 2 (continued): $2y'' - y' - y = \frac{3e^{\frac{3}{2}t}}{1 + e^t}$

► Integrate:

$$\begin{aligned} u_1(t) &= \int -\frac{e^{2t}}{1+e^t} dt \quad \text{substitute } p = e^t, dp = e^t dt \\ &= \int -\frac{pd़p}{1+p} = \int \left(-1 + \frac{1}{1+p}\right) dp = -p + \ln|1+p| + C_1 \\ &= -e^t + \ln|1+e^t| + C_1 \\ &= -e^t + \ln(1+e^t) + C_1, \end{aligned}$$

$$\begin{aligned} u_2(t) &= \int \frac{e^{\frac{1}{2}t}}{1+e^t} dt \quad \text{substitute } q = e^{t/2}, dq = \frac{1}{2}e^{t/2} dt \\ &= \int \frac{2dq}{1+q^2} = 2 \arctan q + C_2 \\ &= 2 \arctan(e^{t/2}) + C_2. \end{aligned}$$

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► Finally, the solutions $y(t)$ of the nonhomog diff eq are obtained:

$$\begin{aligned} y(t) &= y_1 u_1 + y_2 u_2 \\ &= e^{-\frac{1}{2}t} [-e^t + \ln(1+e^t) + C_1] + e^t [2 \arctan(e^{t/2}) + C_2] \\ &= -e^{\frac{1}{2}t} + e^{-\frac{1}{2}t} \ln(1+e^t) + 2e^t \arctan(e^{\frac{1}{2}t}) + C_1 e^{-\frac{1}{2}t} + C_2 e^t. \end{aligned}$$

Example Solve $(1+t)y'' + (-1-2t)y' + ty = \frac{e^t}{1+t}$,
given that complementary solutions are $y_c(t) = C_1 e^t + C_2 e^t \ln|1+t|$.

Example Solve $(1+t)y'' + (-1-2t)y' + ty = \frac{e^t}{1+t}$,

given that complementary solutions are $y_c(t) = C_1 e^t + C_2 e^t \ln|1+t|$.

Solution • $y_c(t) = C_1 y_1(t) + C_2 y_2(t)$ with $y_1(t) = e^t$, $y_2(t) = e^t \ln|1+t|$

• A fund. matrix $M(t) = \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix}$

• Set $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y \\ y' \end{bmatrix} = M(t) \vec{u}(t)$.

The Diff Eq. for $\vec{u}(t)$ is: $\frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ f(t)/a_2(t) \end{bmatrix}$

• Integrate:

$$y(t) = y_1(t)u_1(t) + y_2(t)u_2(t)$$

Example Solve $(1+t)y'' + (-1-2t)y' + ty = \frac{e^t}{1+t}$,

given that complementary solutions are $y_C(t) = C_1 e^t + C_2 e^t \ln|1+t|$.

Solution • $y_C(t) = C_1 y_1(t) + C_2 y_2(t)$ with $y_1(t) = e^t$, $y_2(t) = e^t \ln|1+t|$

- A fund. matrix $M(t) = \begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} = \begin{bmatrix} e^t & e^t \ln|1+t| \\ e^t & e^t \ln|1+t| + \frac{e^t}{1+t} \end{bmatrix}$.

- Set $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y \\ y' \end{bmatrix} = M(t) \vec{u}(t)$.

The Diff Eq for $\vec{u}(t)$ is: $\frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ f(t)/a_2(t) \end{bmatrix} = M(t)^{-1} \begin{bmatrix} 0 \\ \frac{e^t}{(1+t)^2} \end{bmatrix}$.

$$\frac{d\vec{u}}{dt} = \frac{1}{\frac{e^{2t}}{1+t}} \begin{bmatrix} e^t \ln|1+t| + \frac{e^t}{1+t} & -e^t \ln|1+t| \\ -e^t & e^t \end{bmatrix} \begin{bmatrix} 0 \\ \frac{e^t}{(1+t)^2} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{\ln|1+t|}{1+t} \\ \frac{1}{1+t} \end{bmatrix}.$$

$$\int -\frac{\ln|1+t|}{1+t} dt = \int s ds = -\frac{1}{2}s^2 + C.$$

↑ Substitute $s = \ln|1+t|$

$$\int \frac{1}{1+t} dt = \ln|1+t| + C.$$

- Integrate: $\vec{u}(t) = \begin{bmatrix} -\frac{1}{2}(\ln|1+t|)^2 + C_1 \\ \ln|1+t| + C_2 \end{bmatrix}$

- $y(t) = y_1(t)u_1(t) + y_2(t)u_2(t) = e^t \left\{ -\frac{1}{2}(\ln|1+t|)^2 + C_1 \right\} + e^t \ln|1+t| \left\{ \ln|1+t| + C_2 \right\}$

$$= \frac{1}{2}e^t (\ln|1+t|)^2 + C_1 e^t + C_2 e^t \ln|1+t|.$$

Example Solve $4y''' + 9y' = \sec \frac{3t}{2}$

Example Solve $4y''' + 9y' = \sec \frac{3t}{2}$

Solution $y(t) = y_p(t) + y_c(t)$.

Step 1 Find $y_c(t)$ and a fund. matrix $M(t)$.

$$\cdot 4\lambda^3 + 9\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = \frac{3}{2}i, \lambda_3 = -\frac{3}{2}i \Rightarrow y_c(t) = C_1 + C_2 \cos \frac{3t}{2} + C_3 \sin \frac{3t}{2}$$

• A fund. matrix $M(t) =$

$$y_1 = 1, y_2 = \cos \frac{3t}{2}, y_3 = \sin \frac{3t}{2}$$

Step 2 Set $\begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} y \\ y' \\ y'' \end{bmatrix} = M(t) \vec{u}(t)$. The Diff Eq for $\vec{u}(t)$ becomes:

$$\frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ 0 \\ \frac{\sec \frac{3t}{2}}{4} \end{bmatrix}$$

Step 3 Integrate $\Rightarrow \vec{u}_p(t) = \left[\quad \right] \Rightarrow y_p(t) = y_1 u_{1p} + y_2 u_{2p} + y_3 u_{3p}$

Step 4 Gen. Sol's of the Nonhomog. Eq :

$$y(t) = y_p(t) + y_c(t)$$

Example Solve $4y''' + 9y' = \sec \frac{3t}{2}$

Solution $y(t) = y_p(t) + y_c(t)$.

Step 1 Find $y_c(t)$ and a fund. matrix $M(t)$.

$$\cdot 4\lambda^3 + 9\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = \frac{3}{2}i, \lambda_3 = -\frac{3}{2}i \Rightarrow y_c(t) = C_1 + C_2 \cos \frac{3t}{2} + C_3 \sin \frac{3t}{2}$$

$$\cdot \text{A fund. matrix } M(t) = \begin{bmatrix} 1 & \cos \frac{3t}{2} & \sin \frac{3t}{2} \\ 0 & -\frac{3}{2} \sin \frac{3t}{2} & \frac{3}{2} \cos \frac{3t}{2} \\ 0 & -\frac{9}{4} \cos \frac{3t}{2} & -\frac{9}{4} \sin \frac{3t}{2} \end{bmatrix} \quad y_1 = 1, y_2 = \cos \frac{3t}{2}, y_3 = \sin \frac{3t}{2}$$

Step 2 Set $\begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} y \\ y' \\ y'' \end{bmatrix} = M(t) \vec{u}(t)$. The Diff Eq for $\vec{u}(t)$ becomes:

$$\frac{d\vec{u}}{dt} = M(t)^{-1} \begin{bmatrix} 0 \\ 0 \\ \frac{\sec \frac{3t}{2}}{4} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \frac{4}{9} \\ 0 & -\frac{2}{3} \sin \frac{3t}{2} & -\frac{4}{9} \cos \frac{3t}{2} \\ 0 & \frac{2}{3} \cos \frac{3t}{2} & -\frac{4}{9} \sin \frac{3t}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \frac{1}{4} \sec \frac{3t}{2} \end{bmatrix} = \begin{bmatrix} \frac{1}{9} \sec \frac{3t}{2} \\ -\frac{1}{9} \\ -\frac{1}{9} \tan \frac{3t}{2} \end{bmatrix}$$

Step 3 Integrate $\Rightarrow \vec{u}_p(t) = \begin{bmatrix} \frac{2}{27} \ln |\sec \frac{3t}{2} + \tan \frac{3t}{2}| \\ -\frac{1}{9}t \\ \frac{2}{27} \ln |\cos \frac{3t}{2}| \end{bmatrix} \Rightarrow y_p(t) = y_1 u_{1p} + y_2 u_{2p} + y_3 u_{3p}$

Step 4 Gen. Sol's of the Nonhomog. Eq :

$$y(t) = y_p(t) + y_c(t) = \frac{2}{27} \ln |\sec \frac{3t}{2} + \tan \frac{3t}{2}| - \frac{1}{9}t \cos \frac{3t}{2} + \frac{2}{27} \sin \frac{3t}{2} \ln |\cos \frac{3t}{2}| + C_1 + C_2 \cos \frac{3t}{2} + C_3 \sin \frac{3t}{2}$$