

Second Order Homogeneous Linear ODEs with Constant Coefficients

Xu-Yan Chen

Diff Eqs: $ay'' + by' + cy = 0$
 $(a \neq 0 \text{ and } a, b, c \text{ are real constants})$

Things to explore:

- ▶ General solutions
- ▶ Initial value problems
- ▶ Graph solutions y vs t
- ▶ Phase portraits in the (y, y') plane
- ▶ Stability/instability of equilibrium $(0, 0)$

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The Solution Method:

- ▶ $a\lambda^2 + b\lambda + c = 0$ (characteristic polynomial)
 $\Rightarrow \lambda_1, \lambda_2$ (characteristic roots)

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| Root structure | General solutions |
|--|---|
| $\lambda_1 \neq \lambda_2$ | $y = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$ |
| $\lambda_1 = \lambda_2$ | $y = C_1 e^{\lambda_1 t} + C_2 t e^{\lambda_1 t}$ |
| $\lambda_{1,2} = \alpha \pm \beta i$ ($\beta > 0$) | $y = C_1 e^{\alpha t} \cos(\beta t) + C_2 e^{\alpha t} \sin(\beta t)$ |

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- ▶ The Initial Value Problem $\begin{cases} ay'' + by' + cy = 0 \\ y(t_0) = y_0, \quad y'(t_0) = y_1 \end{cases}$

Initial condition $\Rightarrow C_1, C_2 \Rightarrow$ Unique solution $y(t)$

2nd Ord Diff Eq

$$ay'' + by' + cy = 0$$

Equivalent System

$$\begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{c}{a} & -\frac{b}{a} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

by setting $(x_1, x_2) = (y, y')$

- **Eigenvalues:** $a\lambda^2 + b\lambda + c = 0 \iff \det(A - \lambda I) = 0$

- **Distinct roots:** $\lambda_1 \neq \lambda_2, \quad y = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$

$$\Rightarrow \begin{bmatrix} y \\ y' \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = C_1 e^{\lambda_1 t} \begin{bmatrix} 1 \\ \lambda_1 \end{bmatrix} + C_2 e^{\lambda_2 t} \begin{bmatrix} 1 \\ \lambda_2 \end{bmatrix}$$

- **Repeated roots:** $\lambda_1 = \lambda_2, \quad y = C_1 e^{\lambda_1 t} + C_2 t e^{\lambda_1 t}$

$$\Rightarrow \begin{bmatrix} y \\ y' \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = C_1 e^{\lambda_1 t} \begin{bmatrix} 1 \\ \lambda_1 \end{bmatrix} + C_2 e^{\lambda_1 t} \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} + \textcolor{red}{t} \begin{bmatrix} 1 \\ \lambda_1 \end{bmatrix} \right)$$

- **Complex roots:** $\lambda_{1,2} = \alpha \pm \beta i, \quad y = C_1 e^{\alpha t} \cos \beta t + C_2 e^{\alpha t} \sin \beta t$

$$\begin{aligned} \Rightarrow \begin{bmatrix} y \\ y' \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = & C_1 e^{\alpha t} \left(\cos(\beta t) \begin{bmatrix} 1 \\ \alpha \end{bmatrix} - \sin(\beta t) \begin{bmatrix} 0 \\ \beta \end{bmatrix} \right) \\ & + C_2 e^{\alpha t} \left(\sin(\beta t) \begin{bmatrix} 1 \\ \alpha \end{bmatrix} + \cos(\beta t) \begin{bmatrix} 0 \\ \beta \end{bmatrix} \right) \end{aligned}$$

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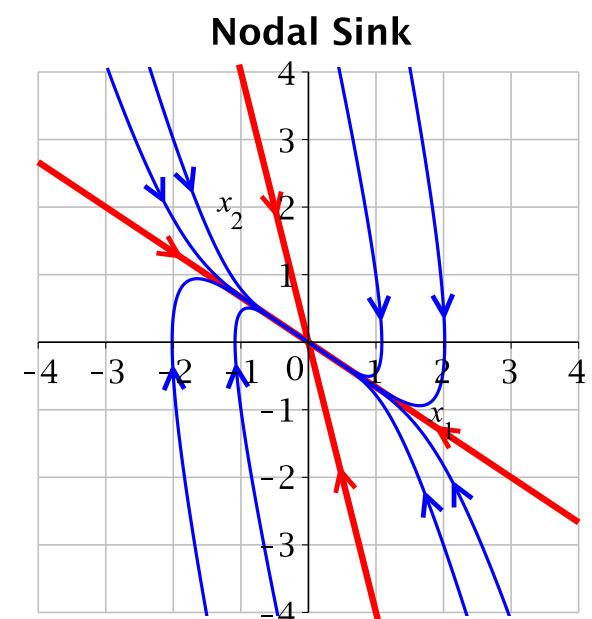
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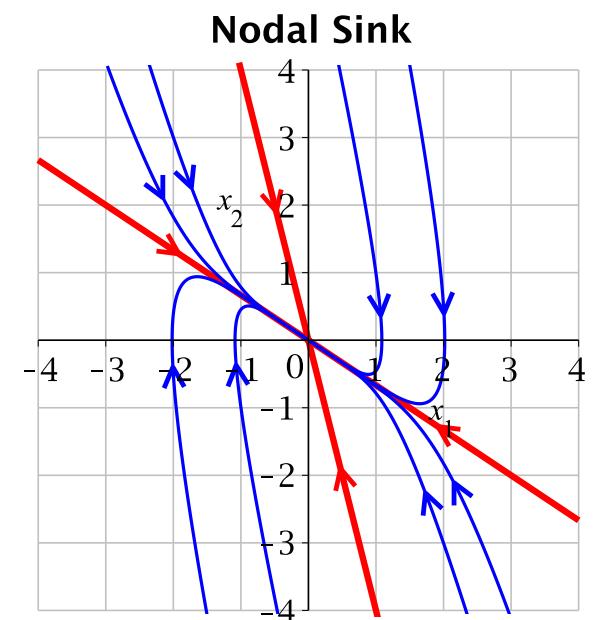
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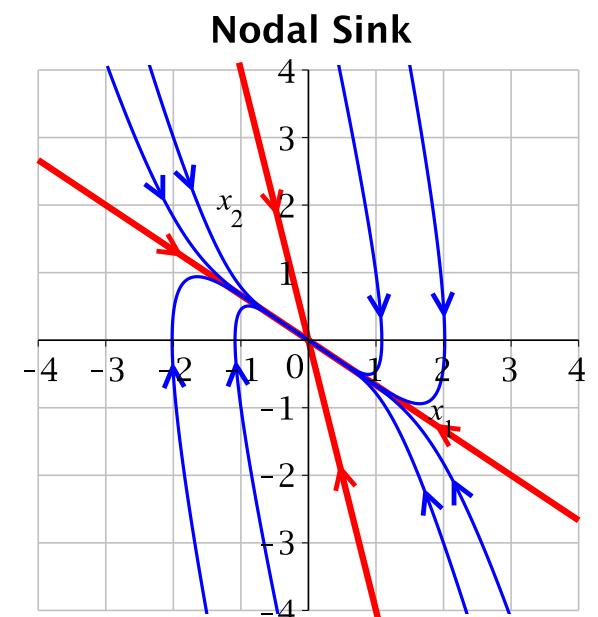
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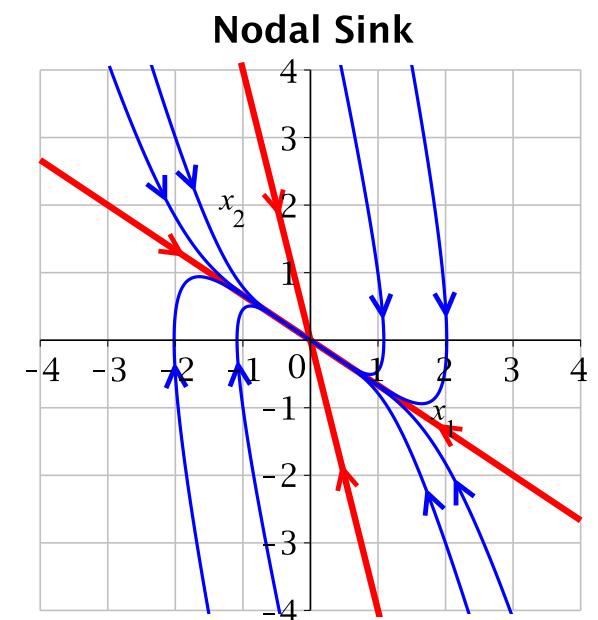
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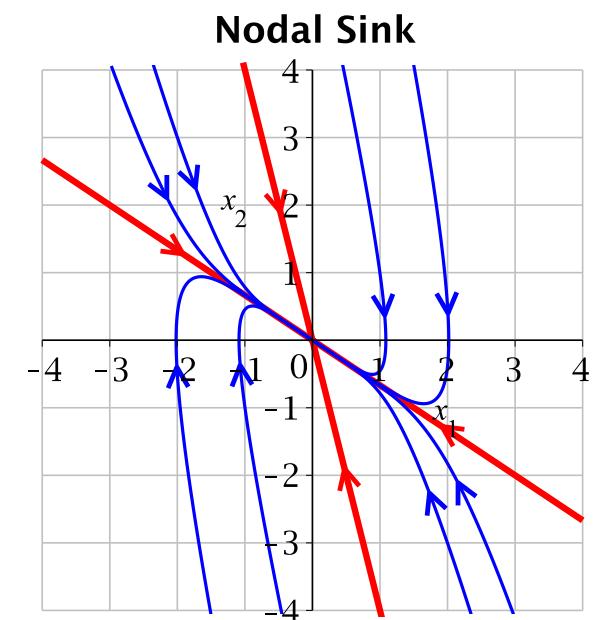
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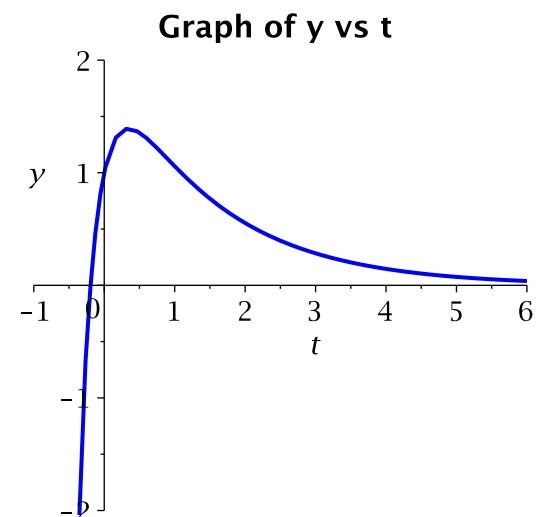


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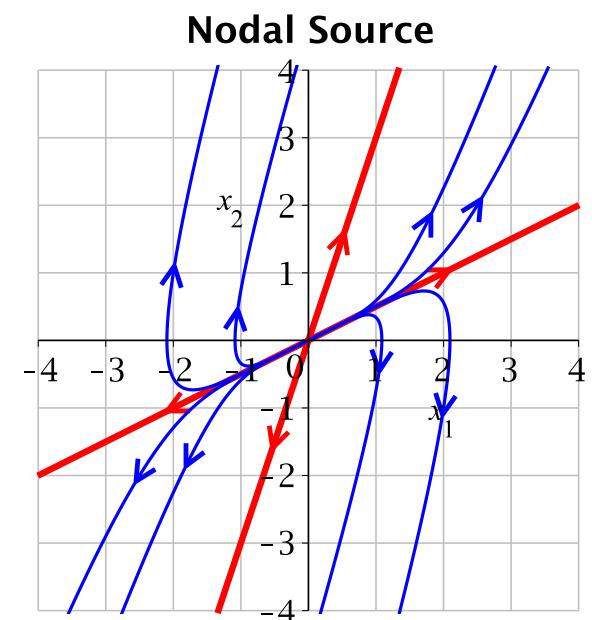
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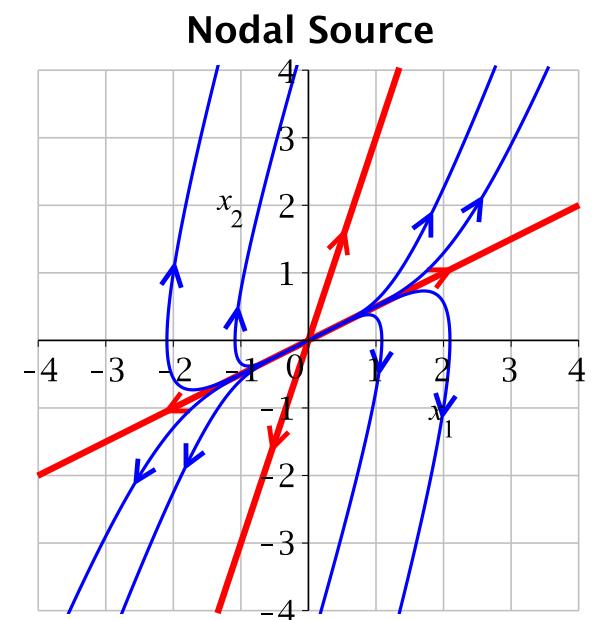
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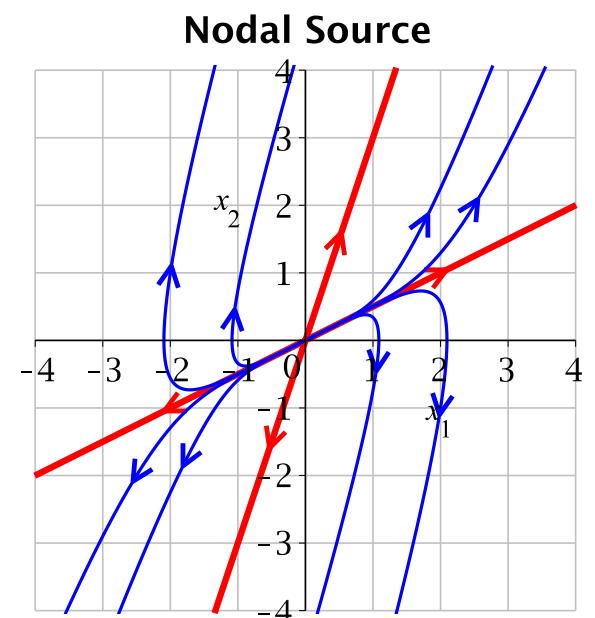
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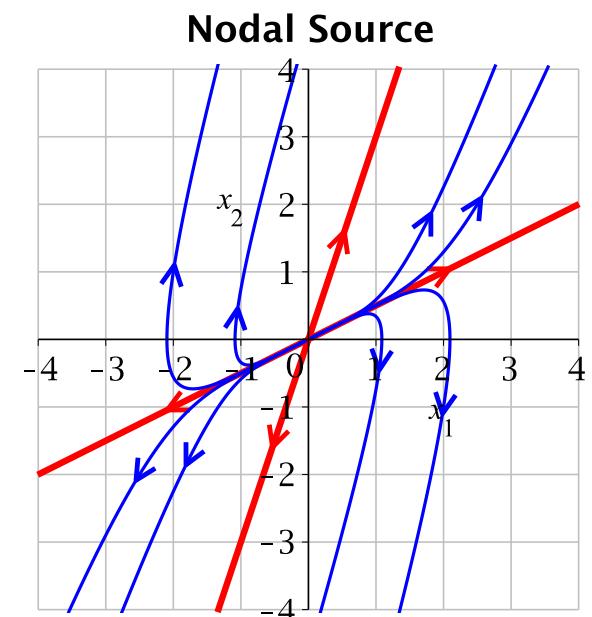
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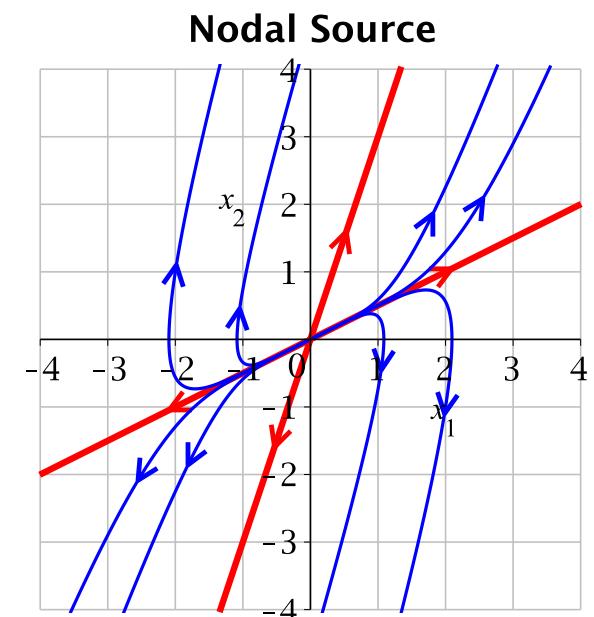
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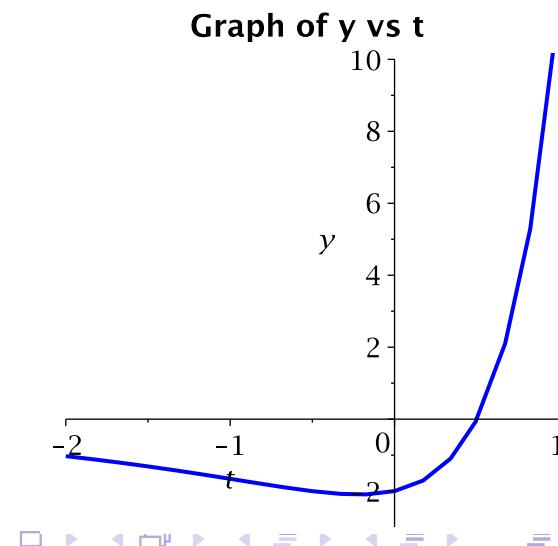


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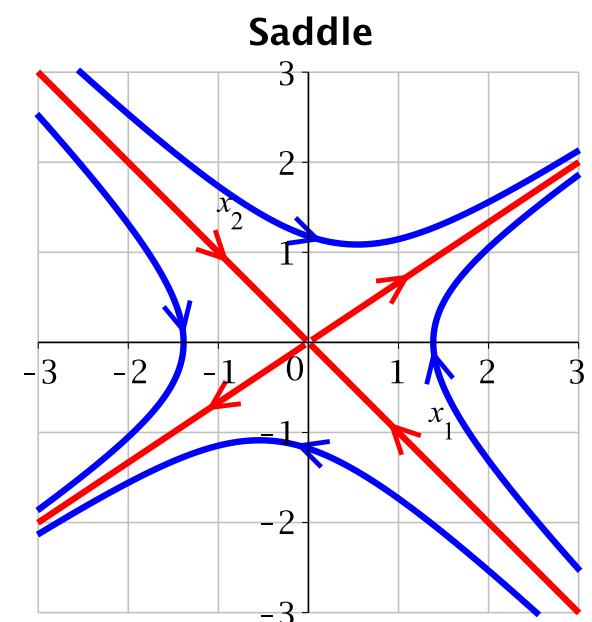
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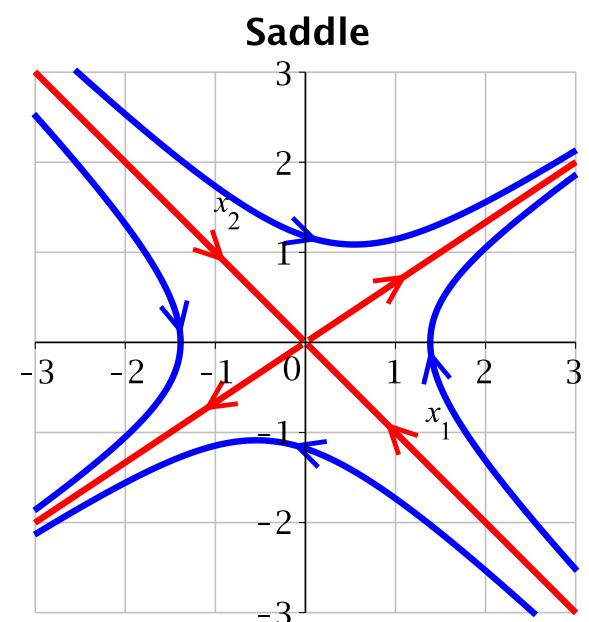
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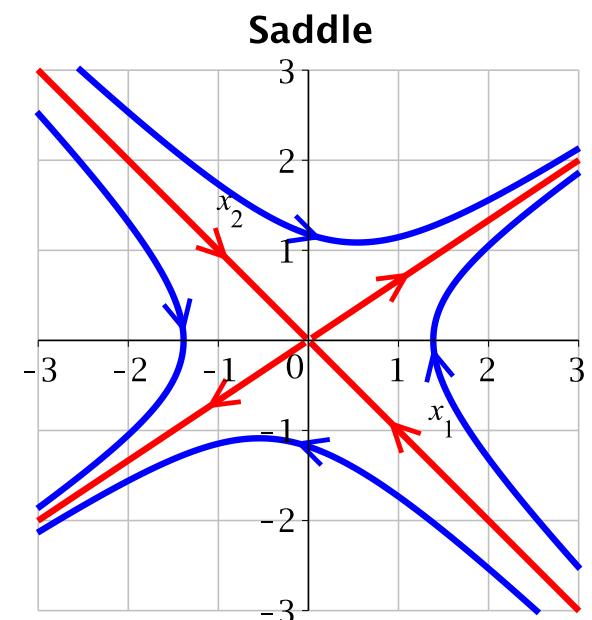
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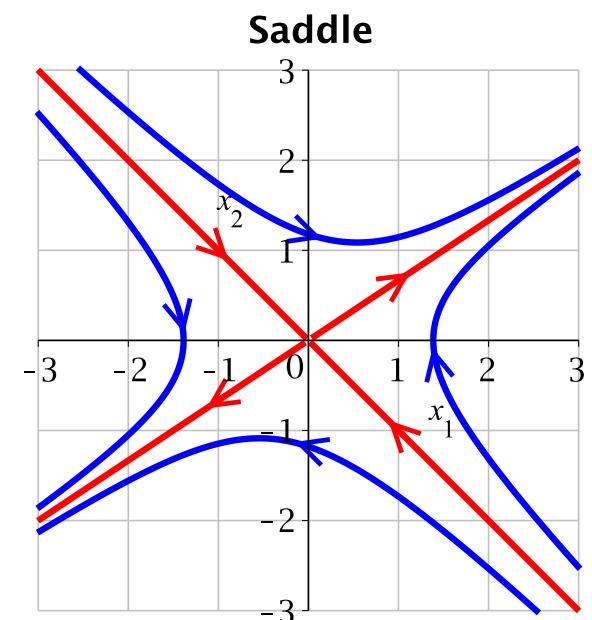
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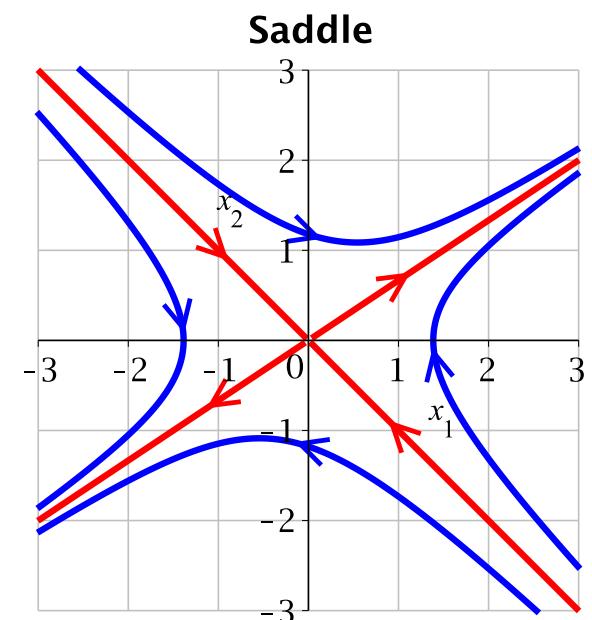
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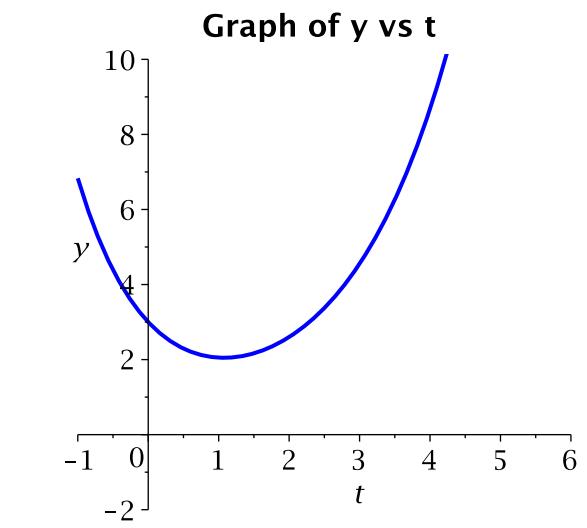


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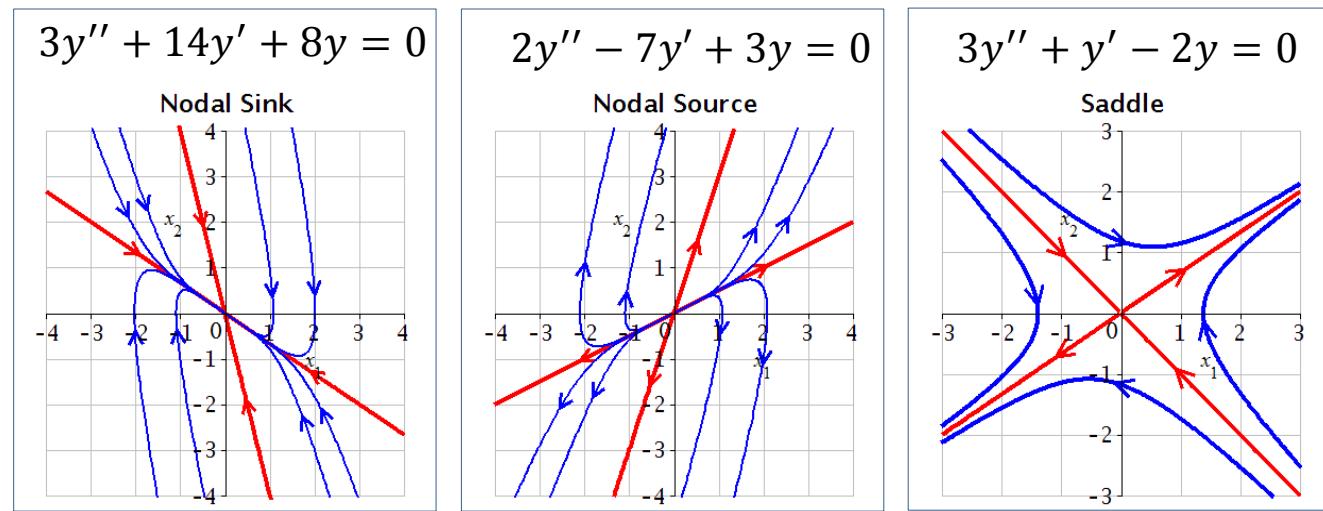
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Special Properties of Phase Portraits of 2nd Order Diff Eqs:

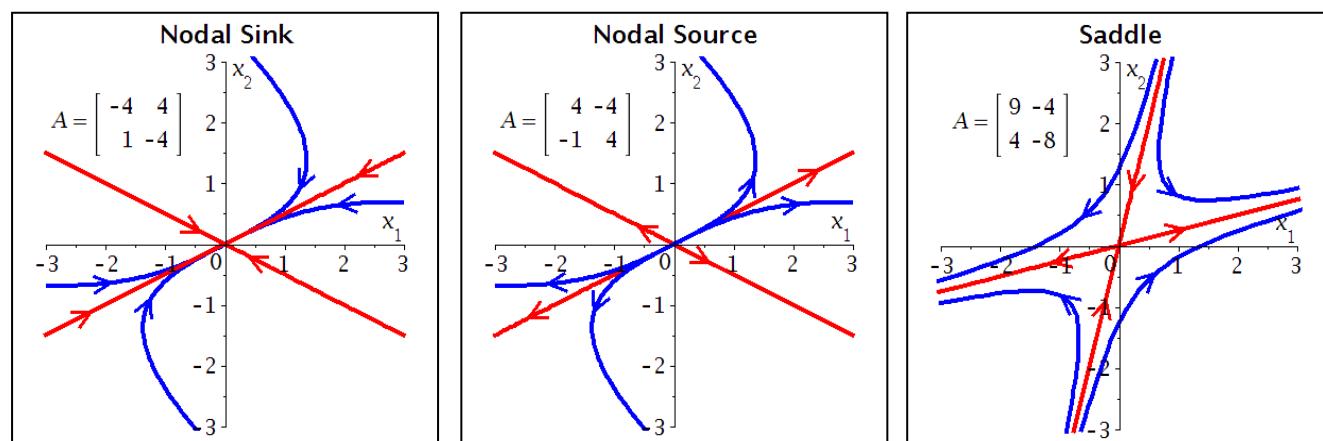
- All curves in the upper half plane go to right.
- All curves in the lower half plane go to left.
- The switching occurs at the x_1 -intercept, in case a curve goes across the x_1 axis.



Warning:

The above are **invalid** for general 2-D systems:

$$\frac{d\vec{x}}{dt} = A\vec{x}$$



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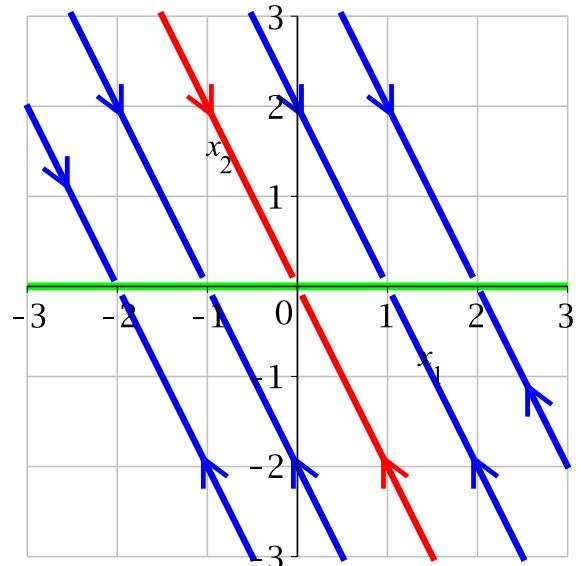
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Attractive Line of Equilibria



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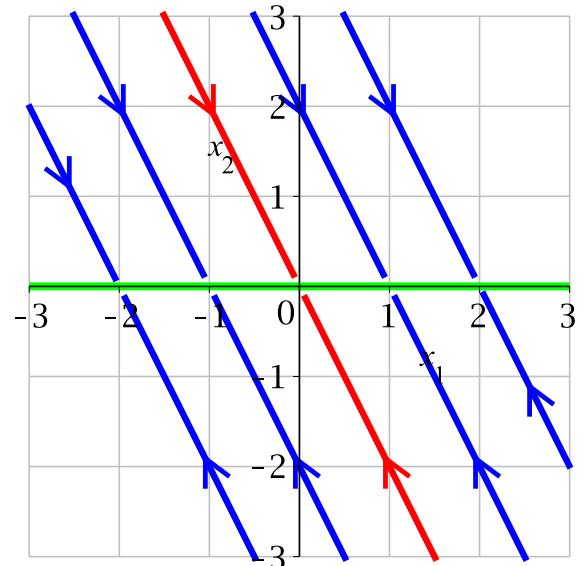
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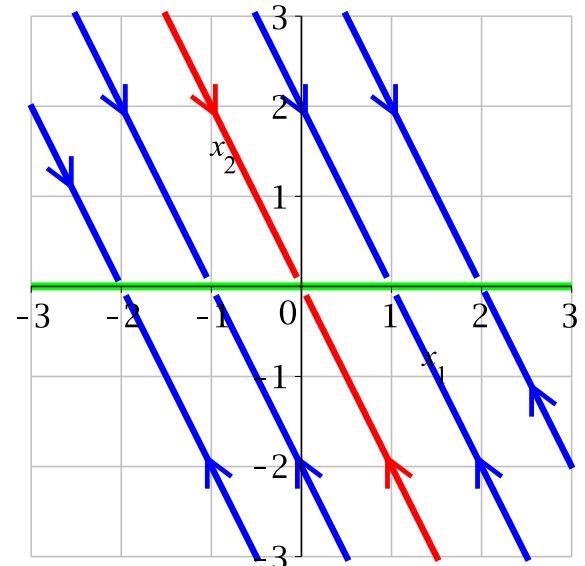
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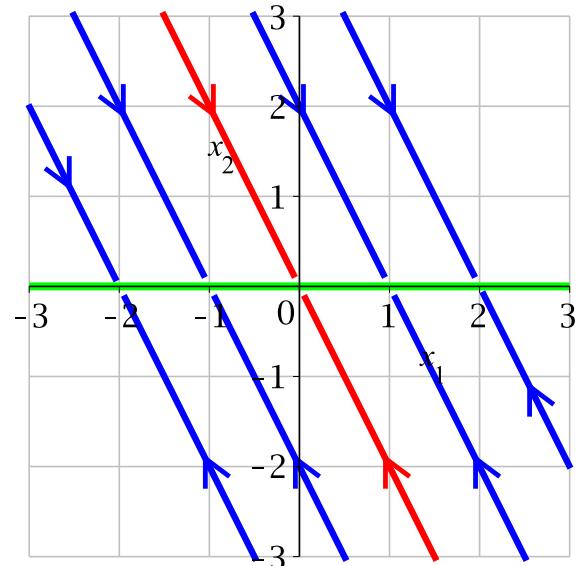
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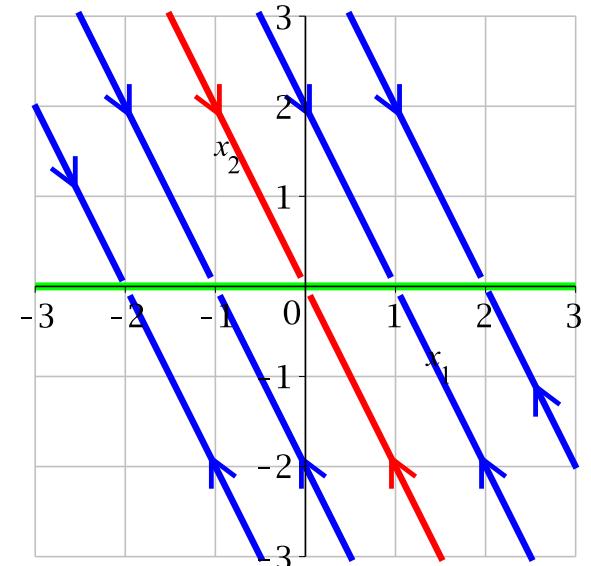
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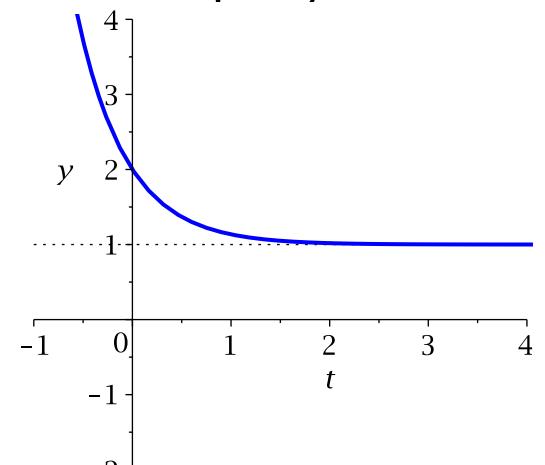
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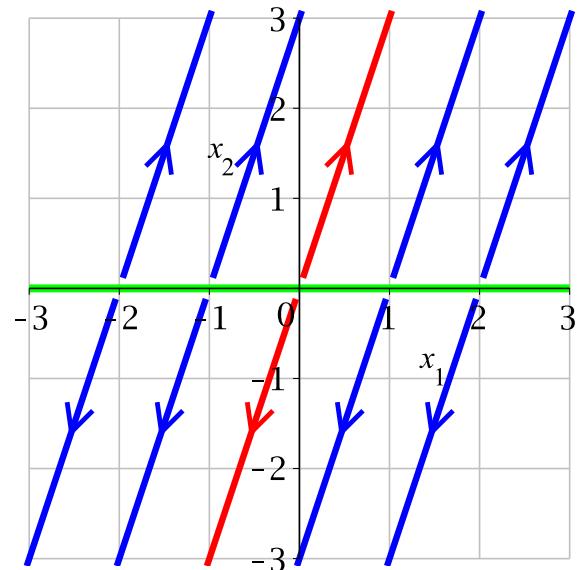
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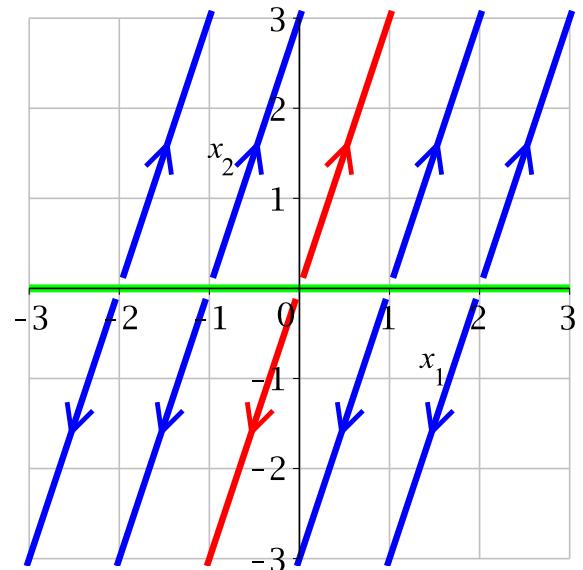
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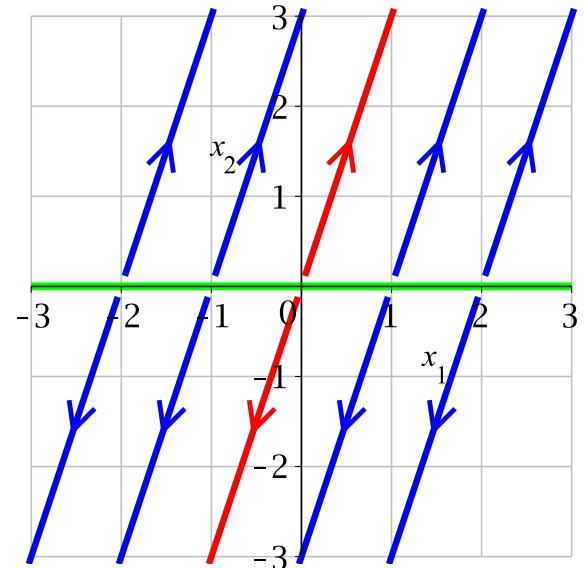
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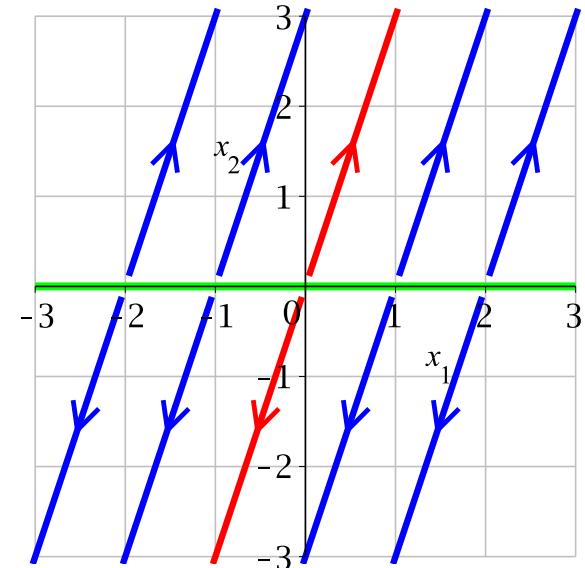
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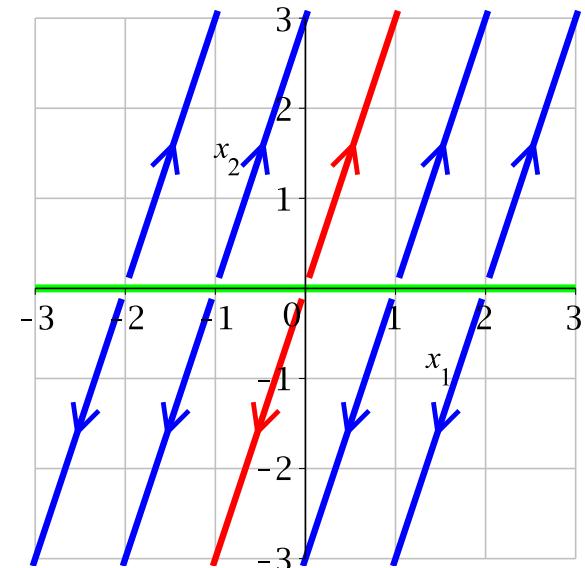
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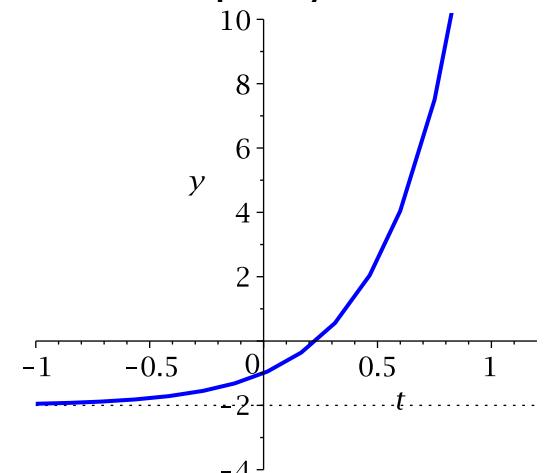
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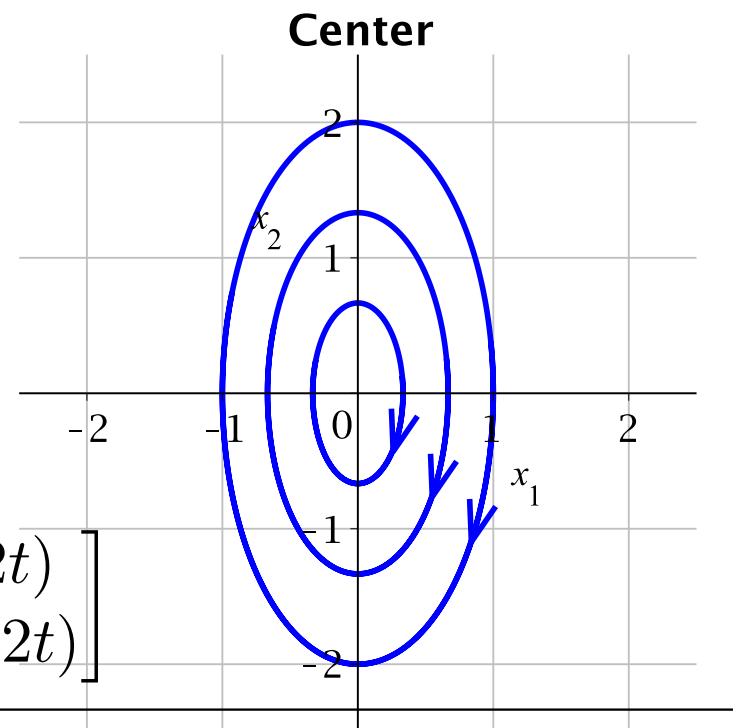
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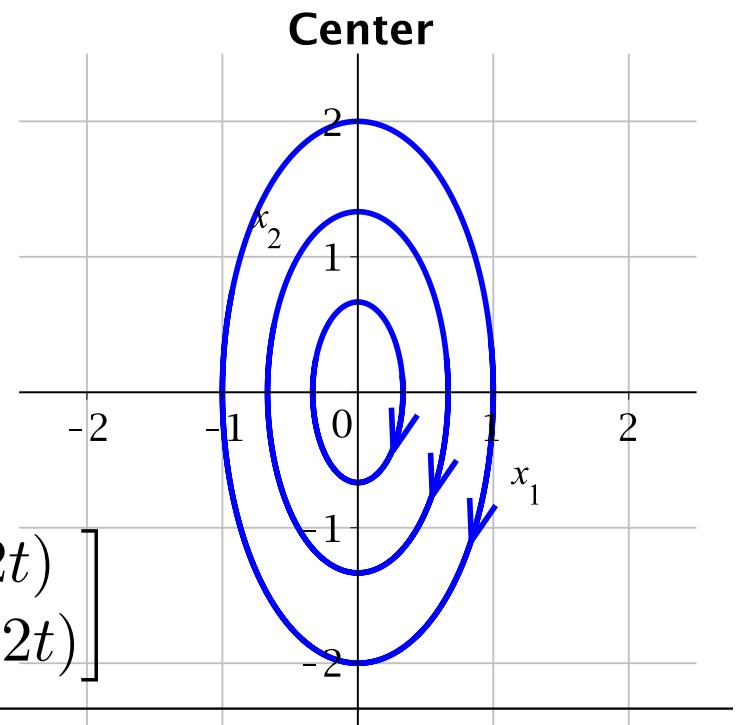
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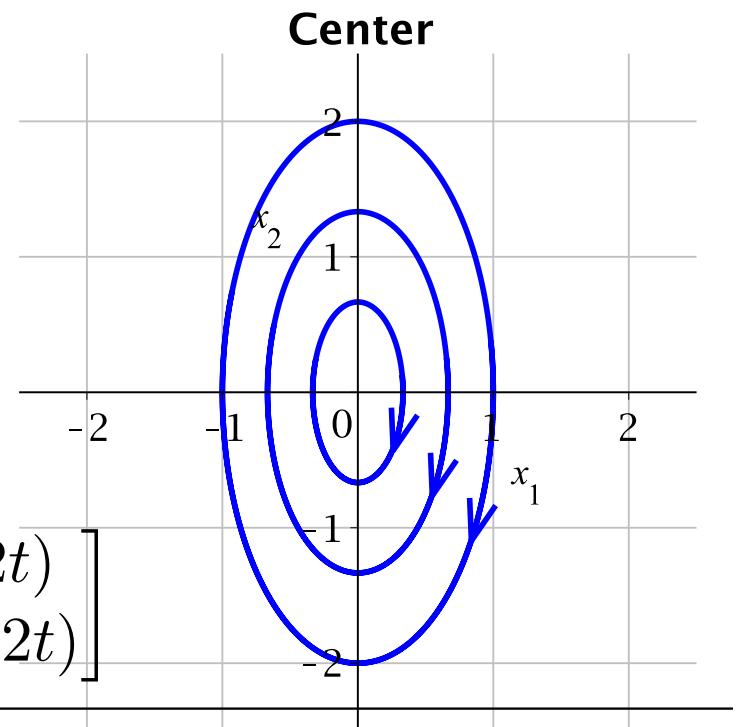
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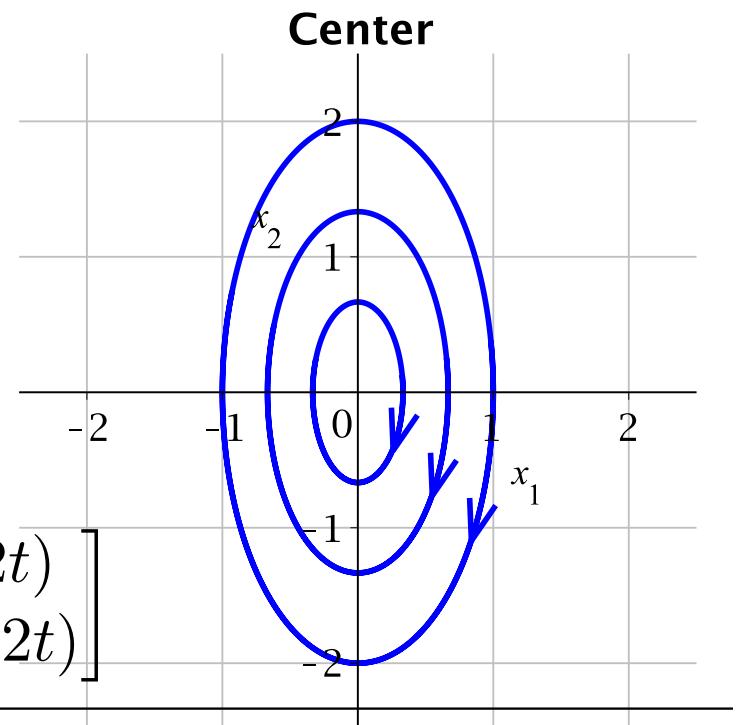
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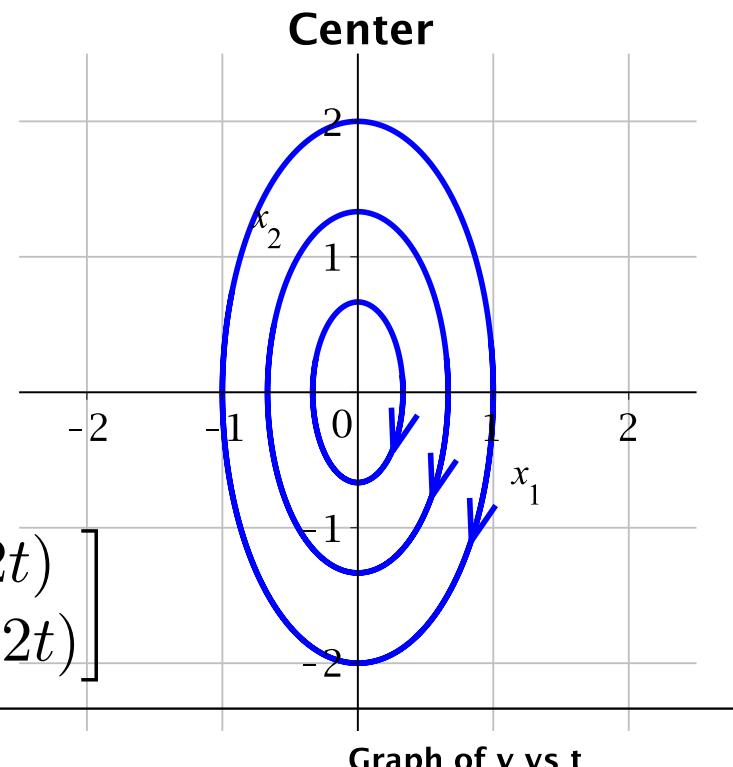
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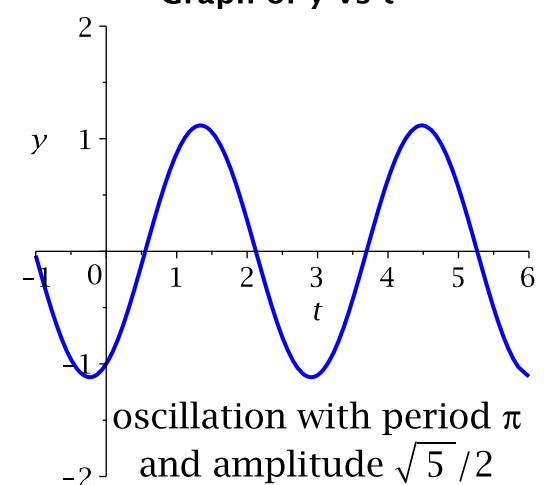


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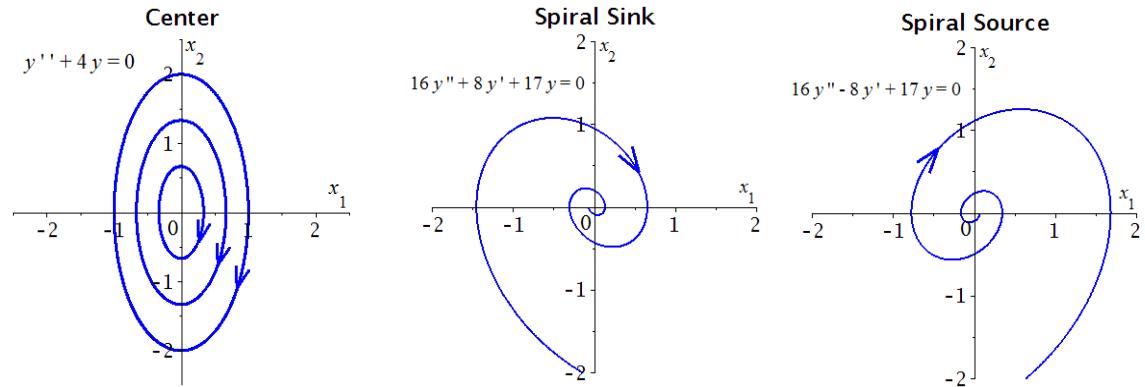
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Phase Portrait of $ay'' + by' + cy = 0$ in the Case of Complex Eigenvalues (i.e. $b^2 - 4ac < 0$)

- The solution trajectories always **rotate clockwise**.



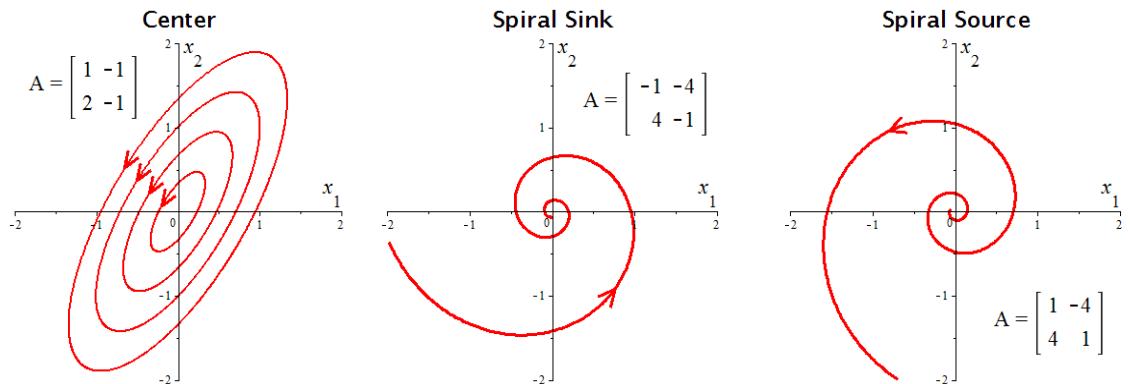
Phase Portrait of $ay'' + cy = 0$ in the Case of a Center (i.e. $ac > 0$, $b = 0$)

- The solution curves are ellipses that **rotate clockwise**.
- The symmetric axes are in the x_1 and x_2 directions.
- The radius in the x_1 direction / The radius in the x_2 direction = $\sqrt{a:c}$

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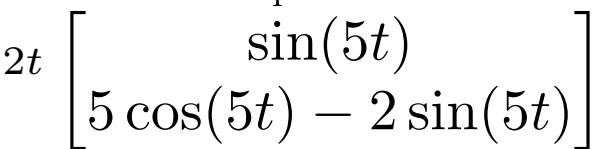
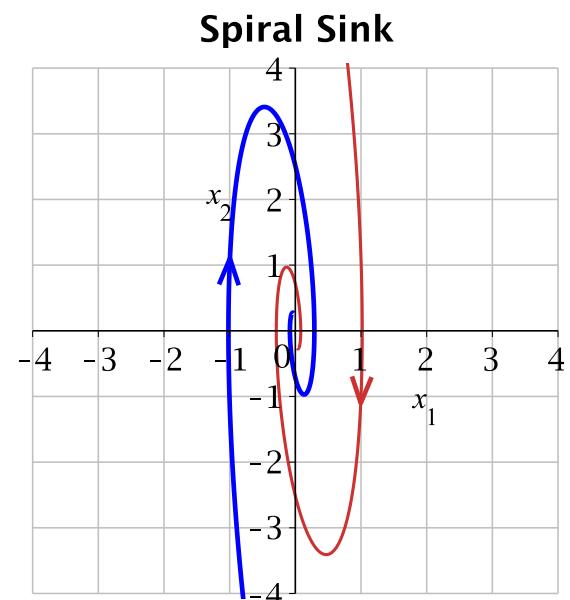
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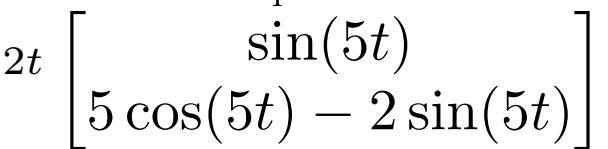
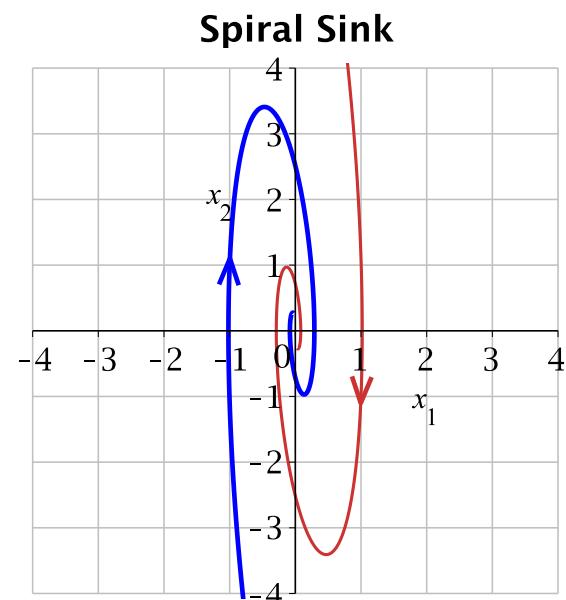
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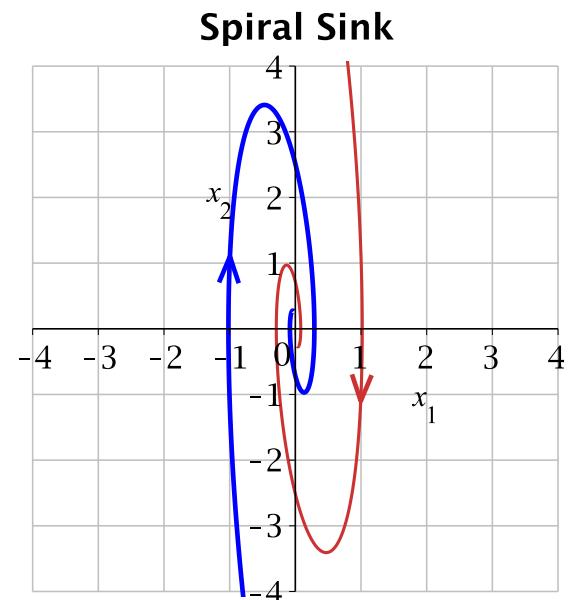
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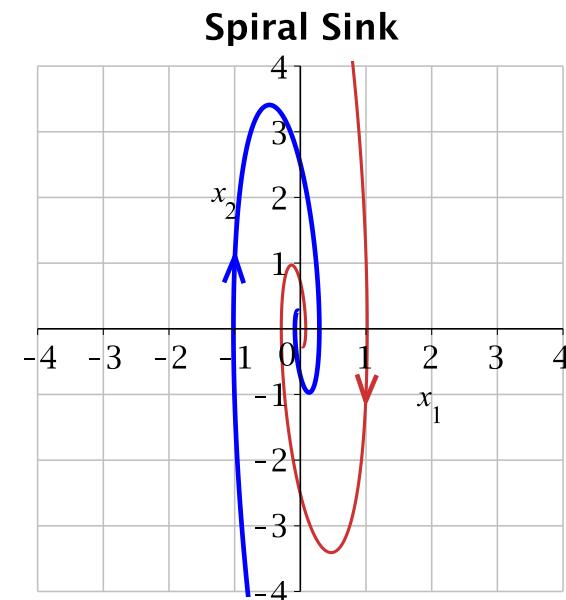
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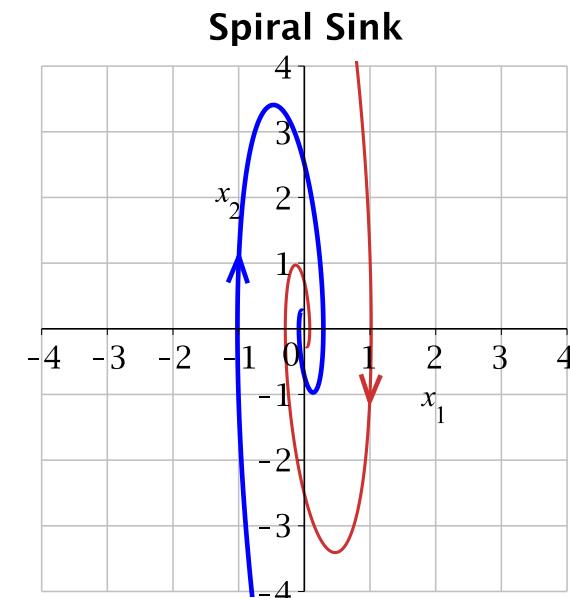
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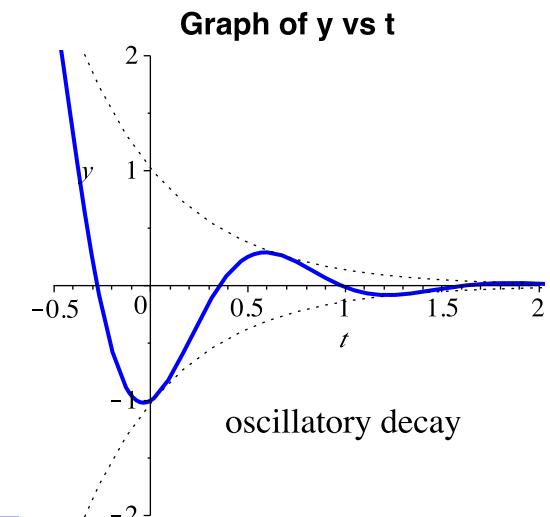


- Initial conditions $y(0) = -1, y'(0) = 1$

$$\begin{cases} C_1 = -1 \\ -2C_1 + 5C_2 = 1 \end{cases} \Rightarrow \begin{cases} C_1 = -1 \\ C_2 = -1/5 \end{cases}$$

The solution of the initial value problem:

$$y = -e^{-2t} \cos(5t) - \frac{1}{5} e^{-2t} \sin(5t)$$



Example: $y'' - 2y' + 17y = 0$

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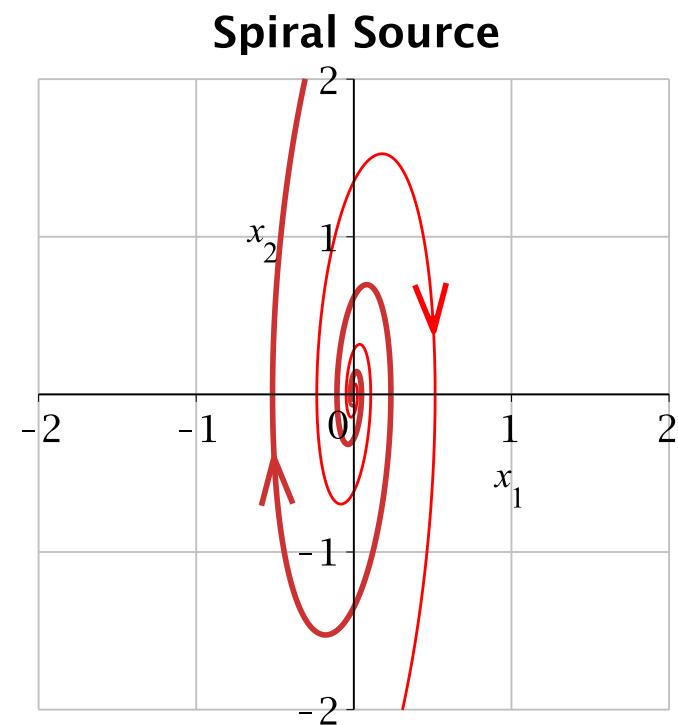
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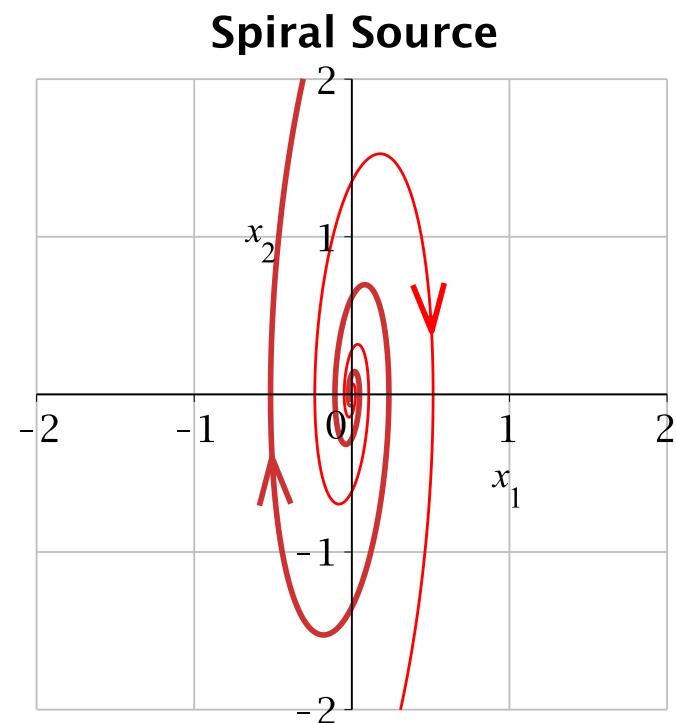
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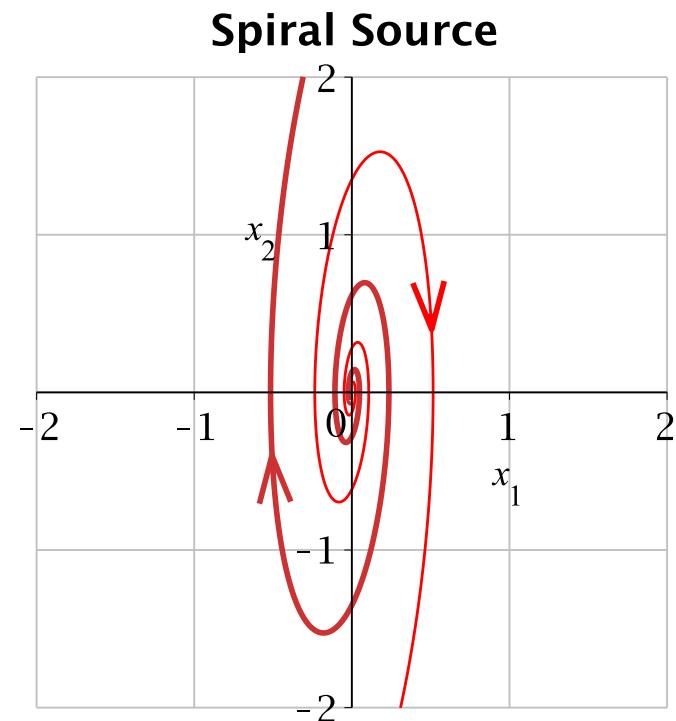
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$$\begin{cases} C_1 = -0.05 \\ C_1 + 4C_2 = 0.1 \end{cases} \Rightarrow \begin{cases} C_1 = -0.05 \\ C_2 = 0.0375 \end{cases}$$

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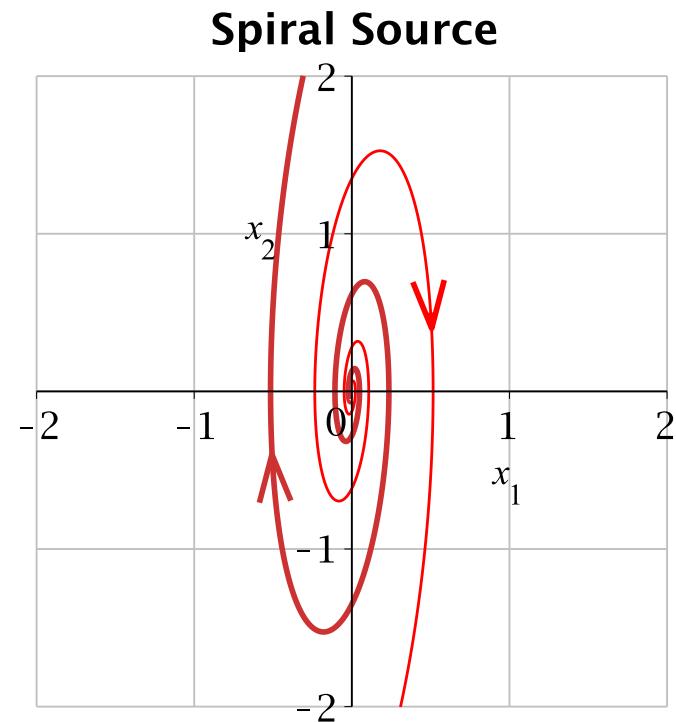
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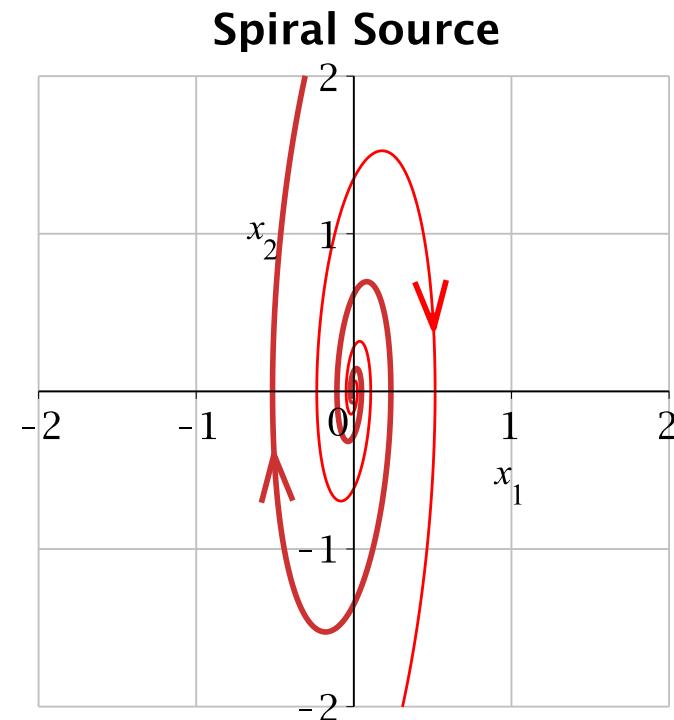
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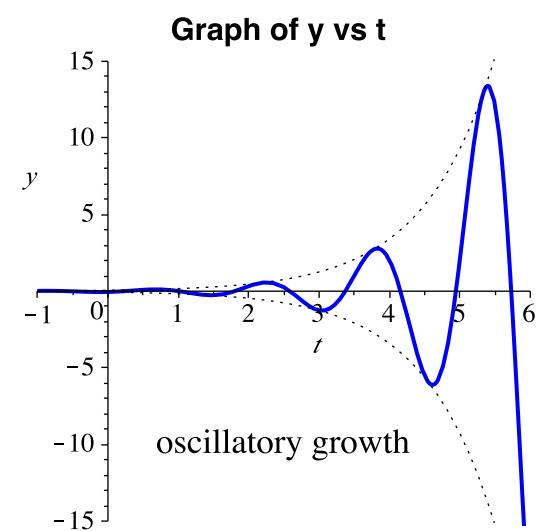


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Example: $4y'' + 12y' + 9y = 0$

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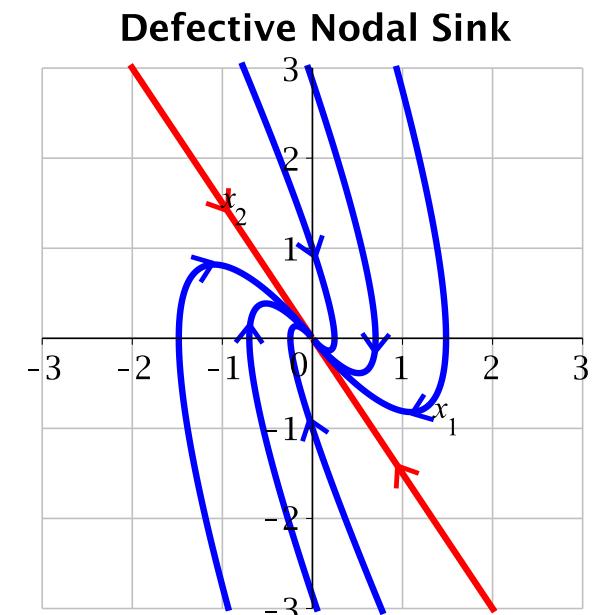
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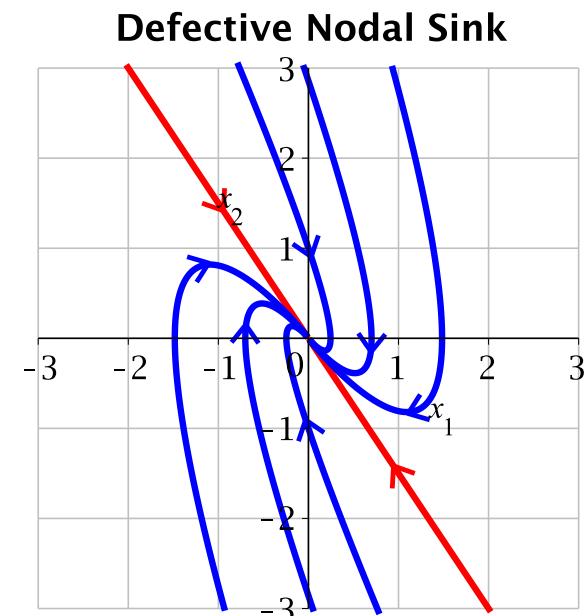
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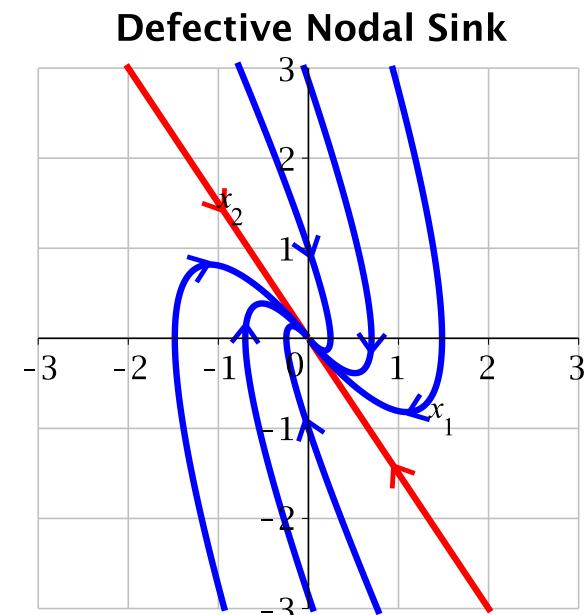
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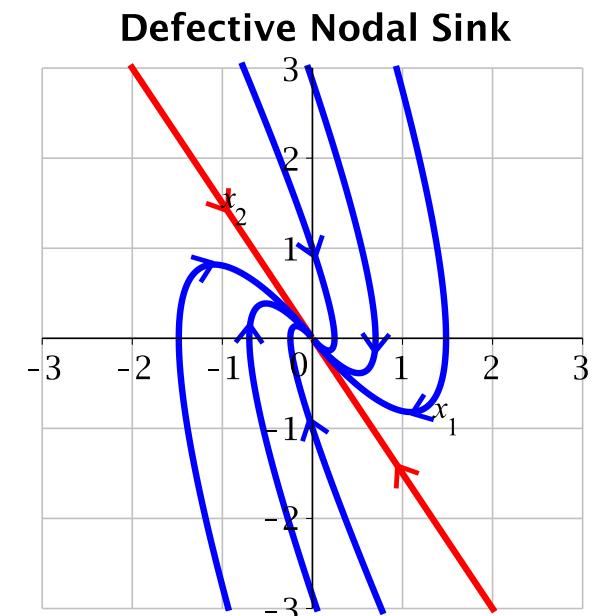
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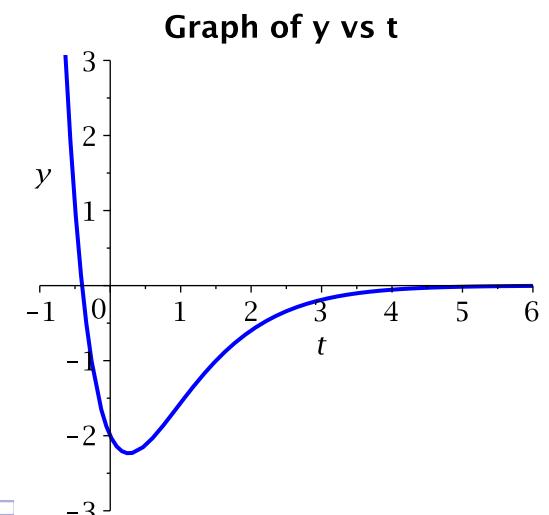
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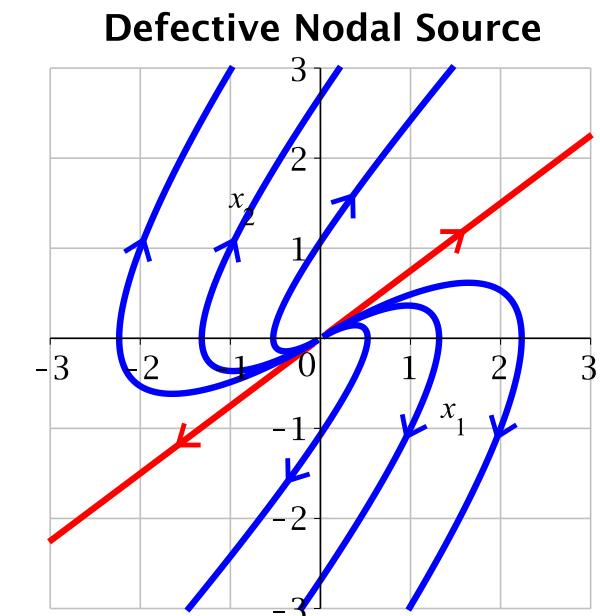
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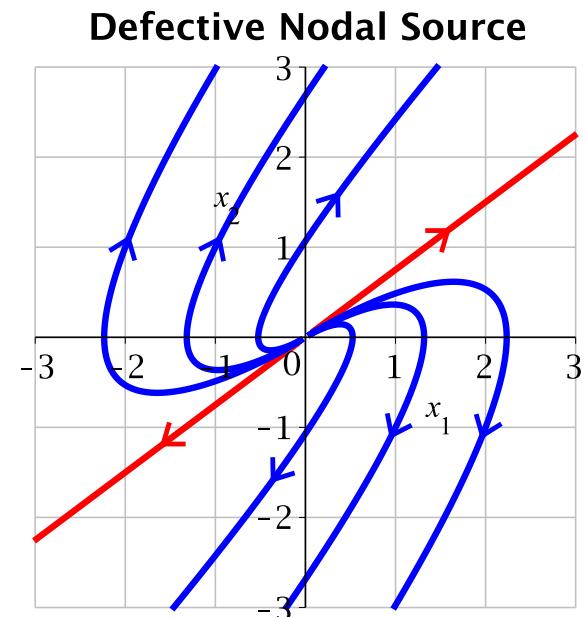
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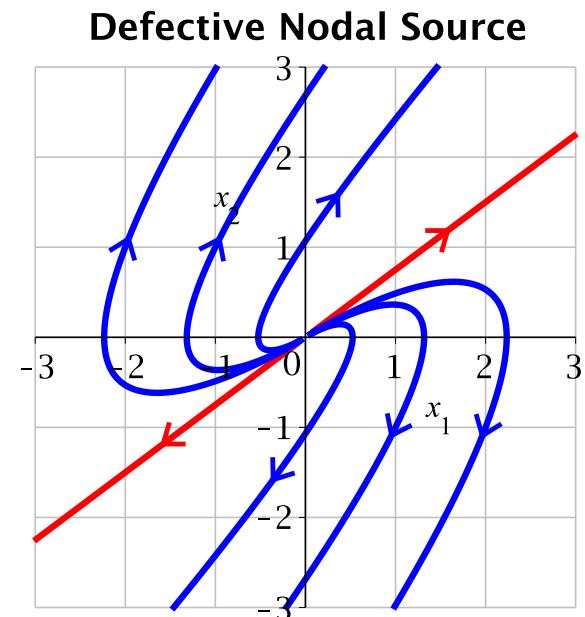
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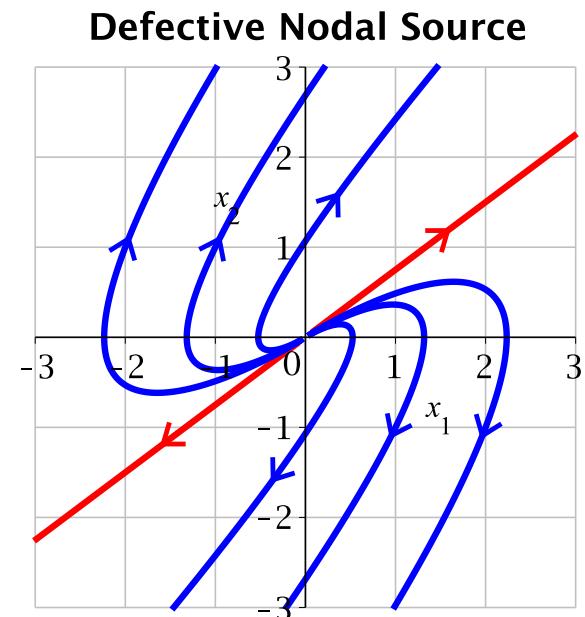
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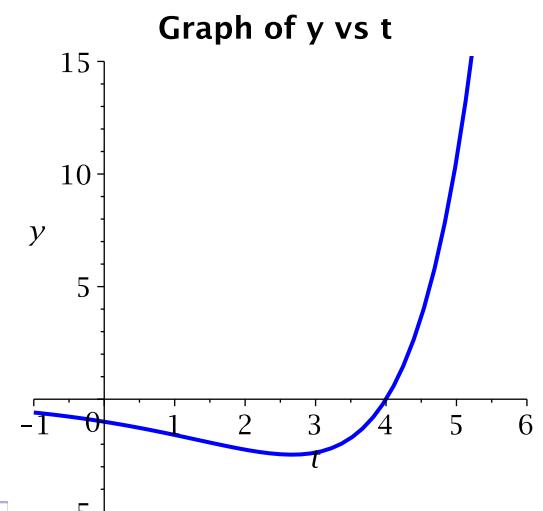
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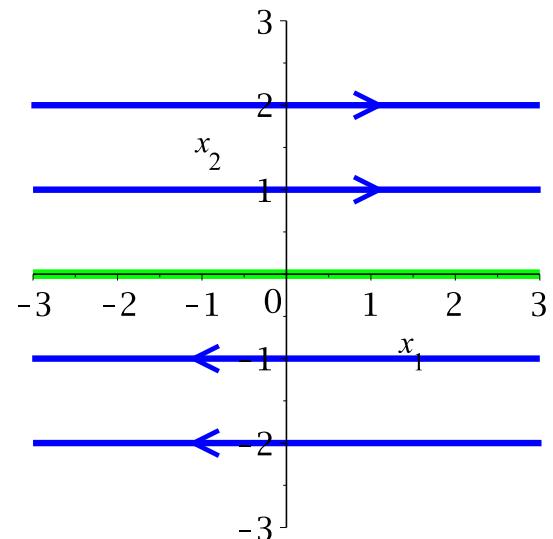
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Laminar Flow (or, Linear Motion with Constant Velocity)



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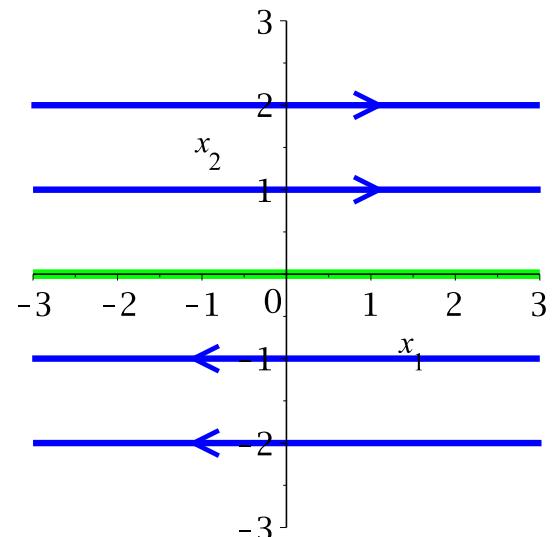
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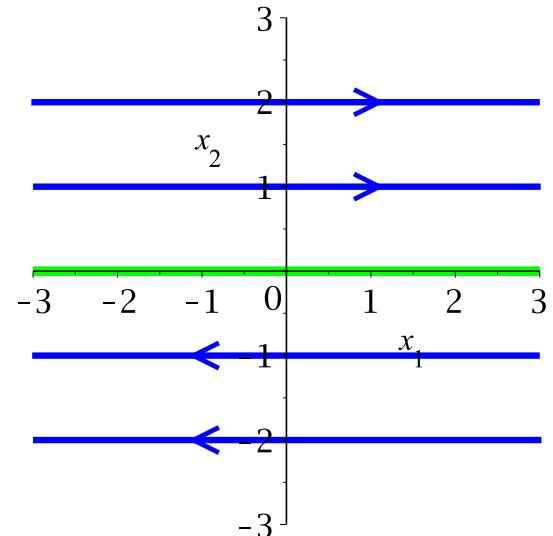
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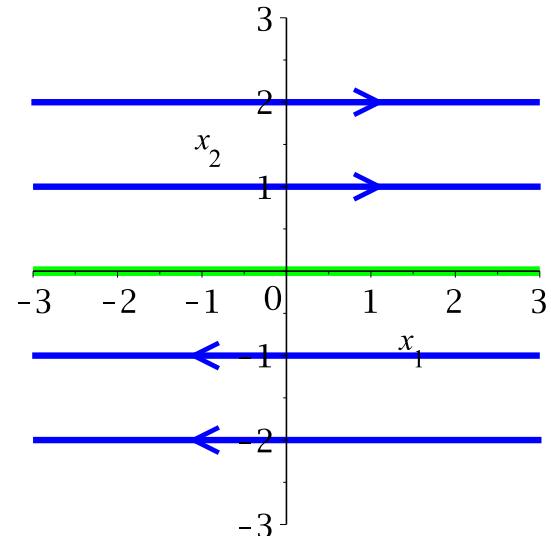
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Graph of y vs t

