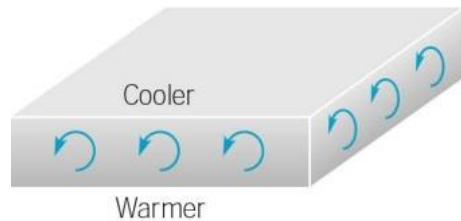


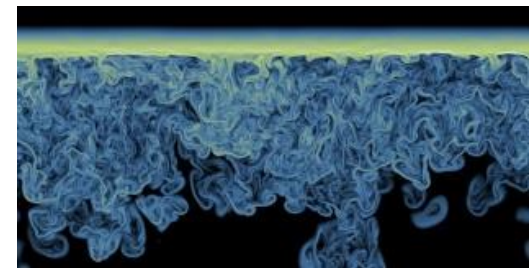
Fluid Dynamics

Asymptotically stable
trivial equilibrium.
Fluid at Rest.

Steady
convective rolls
(clockwise & counterclockwise)



Complicated
turbulent flows.
Impossibility of forecasting.



ΔT

Lorenz Equations

Asymptotically
stable
equilibrium $(0,0,0)$

$r=1$

$(0,0,0)$ becomes
unstable.
Two new asympt
stable equilibria.

$r=470/19$

All equilibria are
unstable.
Chaotic solutions.
Unpredictable behavior.
Strange Attractor.

r

Lorenz Equations

$$\begin{cases} \frac{dx}{dt} = \sigma(-x+y) \\ \frac{dy}{dt} = r x - y - xz \\ \frac{dz}{dt} = -b z + xy \end{cases}$$

$$\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = r x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3} z + xy \end{cases}$$

Summary Let $\sigma = 10$, $b = \frac{8}{3}$.

Increasing r , the asymptotics of the system will change from an attractive equilibrium to a strange attractor with chaotic dynamics.

• Find equilibria

eg. $r=5$

$$\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 5x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{cases}$$

$$\begin{cases} \textcircled{1} & 10(-x+y) = 0 \\ \textcircled{2} & 5x - y - xz = 0 \\ \textcircled{3} & -\frac{8}{3}z + xy = 0 \end{cases}$$

$$\textcircled{1} \Rightarrow \textcircled{4} \quad y = x$$

$$\textcircled{3} \Rightarrow \textcircled{5} \quad z = \frac{3}{8}xy = \frac{3}{8}x^2$$

Plug $\textcircled{4}$ $\textcircled{5}$ in $\textcircled{2}$:

$$5x - x - x\left(\frac{3}{8}x^2\right) = 0, \quad x\left(4 - \frac{3}{8}x^2\right) = 0$$

$$x=0, \quad x = \sqrt{32/3} = \frac{4}{3}\sqrt{6}, \quad x = -\sqrt{32/3} = -\frac{4}{3}\sqrt{6}$$

$\textcircled{4}$ $\textcircled{5}$

• $x=0 \Rightarrow y=0, z=0$.

• $x = \frac{4}{3}\sqrt{6} \Rightarrow y = \frac{4}{3}\sqrt{6}, z = \frac{3}{8}\left(\frac{4}{3}\sqrt{6}\right)^2 = 4$.

• $x = -\frac{4}{3}\sqrt{6} \Rightarrow y = -\frac{4}{3}\sqrt{6}, z = \frac{3}{8}\left(-\frac{4}{3}\sqrt{6}\right)^2 = 4$.

• Three Equilibria: $(0,0,0), \left(\frac{4}{3}\sqrt{6}, \frac{4}{3}\sqrt{6}, 4\right), \left(-\frac{4}{3}\sqrt{6}, -\frac{4}{3}\sqrt{6}, 4\right)$.

Construct Linear Approximating System Near an Equilibrium.

$$\begin{cases} \frac{dx}{dt} = 10(-x+y) & f_1(x,y,z) = 10(-x+y) \\ \frac{dy}{dt} = r x - y - xz & f_2(x,y,z) = r x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy & f_3(x,y,z) = -\frac{8}{3}z + xy \end{cases}$$

• Let (a,b,c) be an equilibrium.

• The Linear Approximating System Near Equilibrium (a,b,c) :

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} J \text{ evaluated} \\ \text{at } (a,b,c) \end{bmatrix} \begin{bmatrix} x-a \\ y-b \\ z-c \end{bmatrix}.$$

• Jacobian Matrix:

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} & \frac{\partial f_1}{\partial z} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} & \frac{\partial f_2}{\partial z} \\ \frac{\partial f_3}{\partial x} & \frac{\partial f_3}{\partial y} & \frac{\partial f_3}{\partial z} \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ r-z & -1 & -x \\ y & x & -\frac{8}{3} \end{bmatrix}$$

When $r < 1$, the system has a unique equilibrium $(0, 0, 0)$,
e.g. which is asympt. stable

$$r = \frac{1}{2} \quad \left\{ \begin{array}{l} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = \frac{1}{2}x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{array} \right.$$

Unique Equilibrium: $(x, y, z) = (0, 0, 0)$

Linear Approximating System near $(0, 0, 0)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ \frac{1}{2} & -1 & 0 \\ 0 & 0 & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

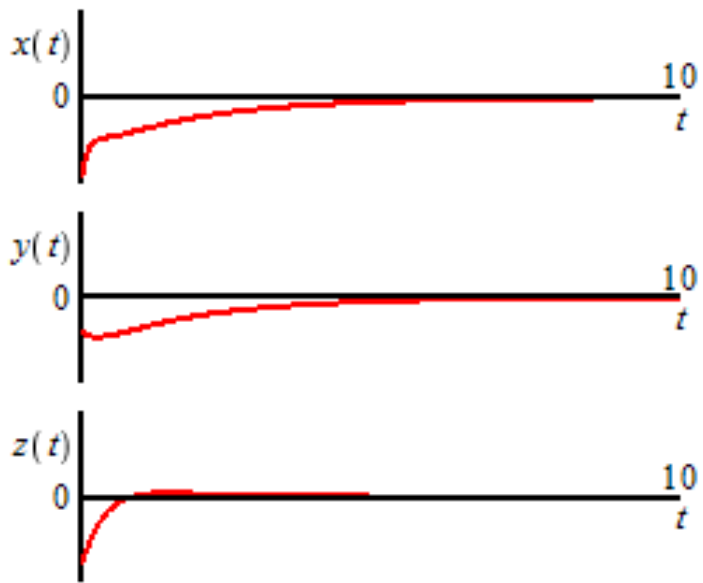
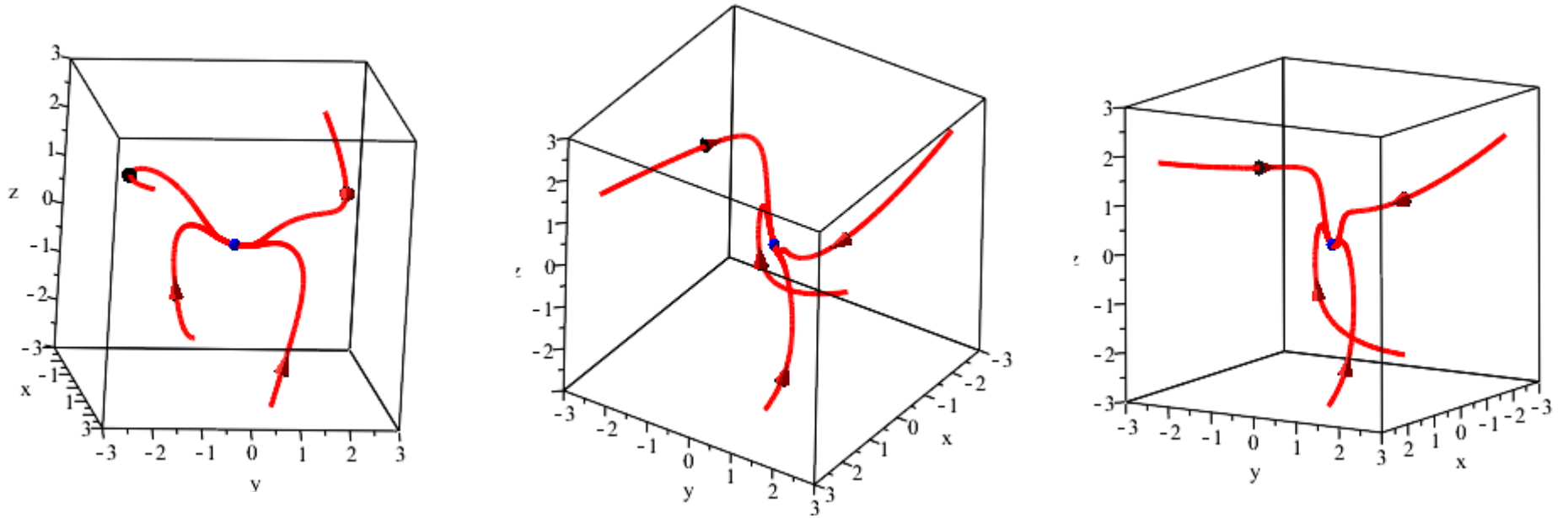
Eigenvalues:

$$\lambda_1 = -\frac{8}{3} = -2.666 \dots$$

$$\lambda_2 = \frac{-11 + \sqrt{101}}{2} = -0.475062190 \dots$$

$$\lambda_3 = \frac{-11 - \sqrt{101}}{2} = -10.52493781 \dots$$

$$r < 1: \quad r = \frac{1}{2}$$



When $r=1$, the equilibrium $(0,0,0)$ becomes degenerate.

$$r=1 \quad \left\{ \begin{array}{l} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 1 \cdot x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{array} \right.$$

Unique Equilibrium: $(x, y, z) = (0, 0, 0)$

Linear Approximating System near $(0, 0, 0)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Eigenvalues:

$$\lambda_1 = -\frac{8}{3}$$

$$\lambda_2 = 0 \quad (\text{neutral eigenvalue})$$

$$\lambda_3 = -11$$

When $1 < r < \frac{470}{19} = 24.73684211 \dots$, there are three equilibria.
 $(0, 0, 0)$ becomes unstable, and
the two new equilibria are asymptotically stable.

e.g. $r=5$ $\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 5x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{cases}$ Three Equilibria:
 $(0, 0, 0)$,
 $(\frac{4}{3}\sqrt{6}, \frac{4}{3}\sqrt{6}, 4)$, $(-\frac{4}{3}\sqrt{6}, -\frac{4}{3}\sqrt{6}, 4)$.

• Linear Approximating System near $(0, 0, 0)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 5 & -1 & 0 \\ 0 & 0 & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Eigenvalues:

$$\lambda_1 = -\frac{8}{3} = -2.666 \dots$$

$$\lambda_2 = \frac{1}{2}(-11 + \sqrt{281}) = 2.8815 \dots$$

$$\lambda_3 = \frac{1}{2}(-11 - \sqrt{281}) = -13.8815 \dots$$

Positive


• $(0, 0, 0)$ is unstable.

When $1 < r < \frac{470}{19} = 24.73684211 \dots$, there are three equilibria.
 $(0, 0, 0)$ becomes unstable, and
the two new equilibria are asymptotically stable.

e.g. $r=5$ $\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 5x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{cases}$ Three Equilibria:
 $(0, 0, 0)$,
 $(\frac{4}{3}\sqrt{6}, \frac{4}{3}\sqrt{6}, 4)$, $(-\frac{4}{3}\sqrt{6}, -\frac{4}{3}\sqrt{6}, 4)$.

• Linear Approximating System near $(\frac{4}{3}\sqrt{6}, \frac{4}{3}\sqrt{6}, 4)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 1 & -1 & -\frac{4}{3}\sqrt{6} \\ \frac{4}{3}\sqrt{6} & \frac{4}{3}\sqrt{6} & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x - \frac{4}{3}\sqrt{6} \\ y - \frac{4}{3}\sqrt{6} \\ z - 4 \end{bmatrix}$$

Eigenvalues:

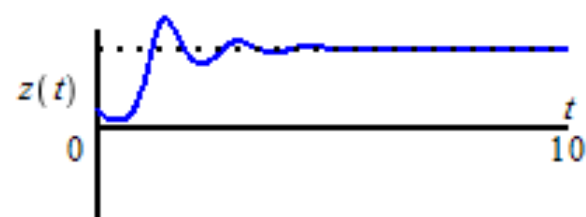
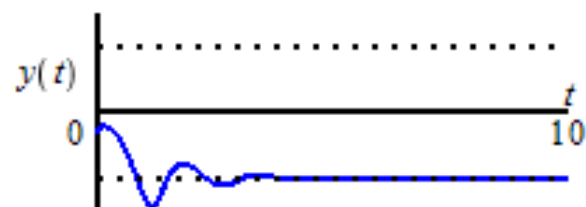
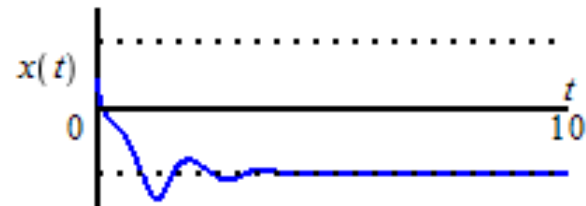
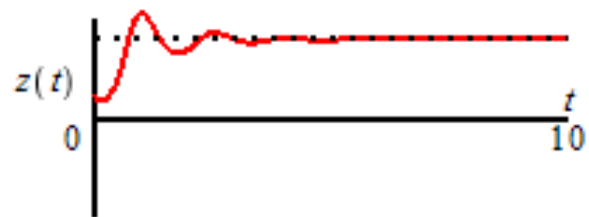
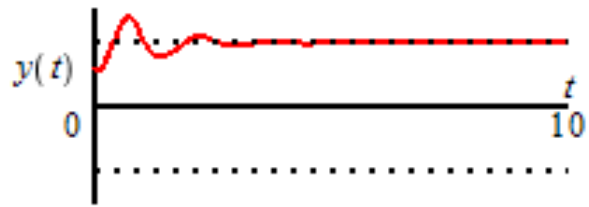
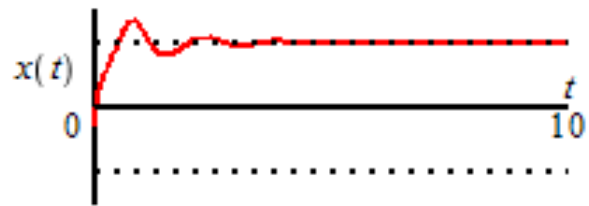
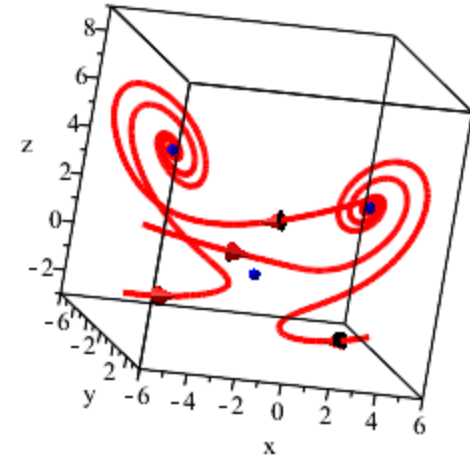
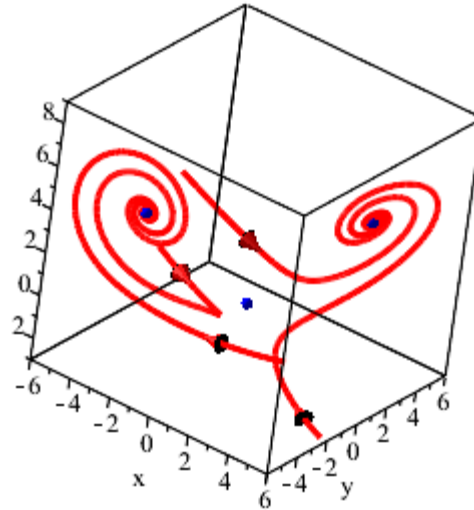
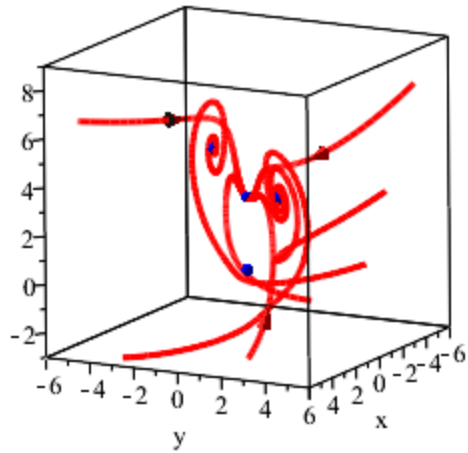
$$\lambda_1 = -11.809 \dots$$

$$\lambda_2 = -0.9287 \dots + 4.14758 \dots i$$

$$\lambda_3 = -0.9287 \dots - 4.14758 \dots i$$

• $(\frac{4}{3}\sqrt{6}, \frac{4}{3}\sqrt{6}, 4)$ is asymptotically stable.

$$1 < r < \frac{470}{19} = 24.73684211: \quad r = 5$$



When $r = \frac{470}{19} = 24.73684211 \dots$, there are three equilibria.

$(0,0,0)$ is still unstable, and

the two nonzero equilibria become degenerate.

$$r = \frac{470}{19}$$

$$\left\{ \begin{array}{l} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = \frac{470}{19}x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{array} \right.$$

Three Equilibria:

$$(0, 0, 0),$$

$$\left(\frac{2}{57}\sqrt{51414}, \frac{2}{57}\sqrt{51414}, \frac{451}{19} \right),$$

$$\left(-\frac{2}{57}\sqrt{51414}, -\frac{2}{57}\sqrt{51414}, \frac{451}{19} \right).$$

• Lin. Approx. System Near $(0,0,0)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ \frac{470}{19} & -1 & 0 \\ 0 & 0 & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Eigenvalues: $\lambda_1 = -8/3 = -2.666 \dots$

$$\lambda_2 = -\frac{11}{2} + \frac{43}{38}\sqrt{209} = 10.859 \dots > 0$$

$$\lambda_3 = -\frac{11}{2} - \frac{43}{38}\sqrt{209} = -21.859 \dots$$

• Lin. Approx. System Near $\left(\frac{2}{57}\sqrt{51414}, \frac{2}{57}\sqrt{51414}, \frac{451}{19} \right)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 1 & -1 & 0 \\ \frac{2}{57}\sqrt{51414} & \frac{2}{57}\sqrt{51414} & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x - \frac{2}{57}\sqrt{51414} \\ y - \frac{2}{57}\sqrt{51414} \\ z - \frac{451}{19} \end{bmatrix}$$

Eigenvalues:

$$\lambda_1 = -\frac{41}{3}$$

$$\lambda_2 = \frac{4}{19}\sqrt{2090}i$$

$$\lambda_3 = -\frac{4}{19}\sqrt{2090}i$$

↗ $\lambda_{2,3}$ are neutral.

When $r > \frac{470}{19} = 24.73684211\dots$, there are three equilibria.

- $(0,0,0)$ is still unstable, and the other two equilibria also become unstable.
- A **Strange attractor** appears. The system exhibits **chaotic dynamics**

e.g. $r=28$ $\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 28x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{cases}$ Three Equilibria:

$(0,0,0)$,
 $(6\sqrt{2}, 6\sqrt{2}, 27), (-6\sqrt{2}, -6\sqrt{2}, 27)$

• Linear Approximating System near $(0,0,0)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 28 & -1 & 0 \\ 0 & 0 & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Eigenvalues:

$$\lambda_1 = -\frac{8}{3} = -2.666\dots$$

$$\lambda_2 = \frac{1}{2}(-11 + \sqrt{1201}) = 11.8277\dots > 0$$

$$\lambda_3 = \frac{1}{2}(-11 - \sqrt{1201}) = -22.8277\dots$$

• $(0,0,0)$ is unstable.

When $r > \frac{470}{19} = 24.73684211\dots$, there are three equilibria.

- $(0,0,0)$ is still unstable, and the other two equilibria also become unstable.
- A **Strange attractor** appears. The system exhibits **chaotic dynamics**.

e.g. $r=28$

$$\begin{cases} \frac{dx}{dt} = 10(-x+y) \\ \frac{dy}{dt} = 28x - y - xz \\ \frac{dz}{dt} = -\frac{8}{3}z + xy \end{cases}$$

Three Equilibria:
 $(0, 0, 0)$,
 $(6\sqrt{2}, 6\sqrt{2}, 27)$, $(-6\sqrt{2}, -6\sqrt{2}, 27)$

- Linear Approximating System near $(6\sqrt{2}, 6\sqrt{2}, 27)$:

$$\frac{d}{dt} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -10 & 10 & 0 \\ 1 & -1 & -6\sqrt{2} \\ 6\sqrt{2} & 6\sqrt{2} & -\frac{8}{3} \end{bmatrix} \begin{bmatrix} x-6\sqrt{2} \\ y-6\sqrt{2} \\ z-27 \end{bmatrix}$$

Eigenvalues:

$$\lambda_1 = -13.85$$

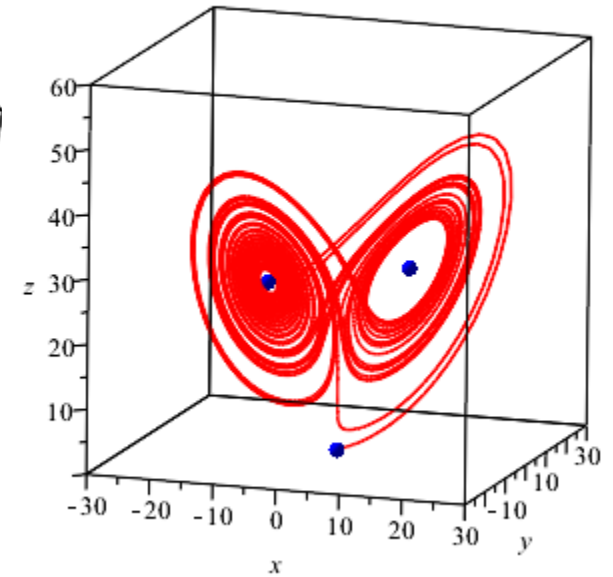
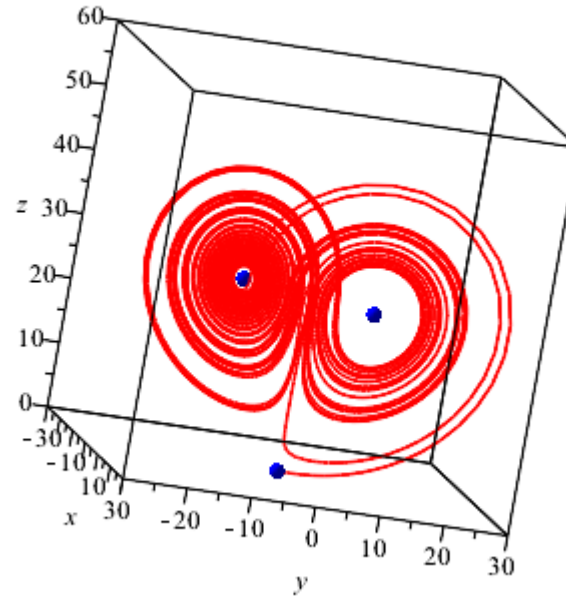
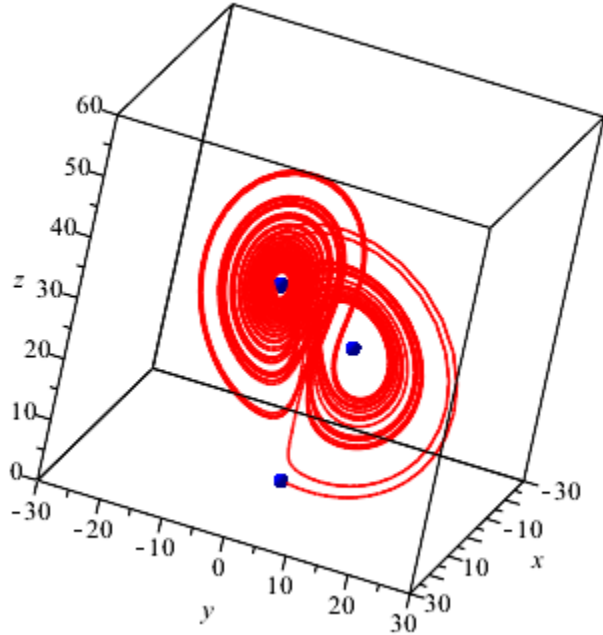
$$\lambda_2 = 0.09\dots + 10.19\dots i$$

$$\lambda_3 = 0.09\dots - 10.19\dots i$$

- $(6\sqrt{2}, 6\sqrt{2}, 27)$ is unstable.

$$r > \frac{470}{19} = 24.73684211: \quad r = 28$$

Strange Attractor



Chaos: Unpredictable solutions.
Sensitive dependence of solutions
on the initial conditions.

Red solution:

$$x(0) = 0.1, y(0) = 0.1, z(0) = 0.1$$

Blue solution:

$$x(0) = 0.1, y(0) = 0.101, z(0) = 0.1$$

