Phase Portraits of 1-D Autonomous Equations

In each of the following problems [1]-[5]: (a) find all equilibrium solutions; (b) determine whether each of the equilibrium solutions is stable, asymptotically stable or unstable; and (c) sketch the phase portrait.

- $[1] \ \frac{dP}{dt} = P(P^2 1)(P 3).$ $[2] \ \frac{dy}{dt} = -(y 1)(y 3)^2.$ $[3] \ \frac{dy}{dt} = \sin(\pi y).$
- $[4] \ \frac{dx}{dt}(t) = \sin^2(\pi x(t)).$
- [5] $\frac{dy}{dt} = f(y)$, where the function f(y) is piecewise defined by:

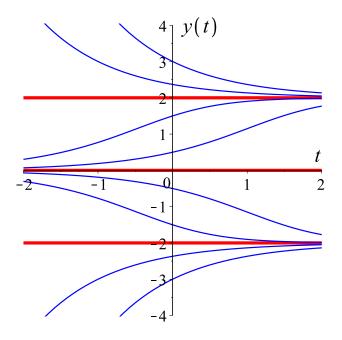
$$f(y) = \begin{cases} 2y & y \le 0, \\ 0 & 0 < y < 1, \\ 1 - y & y \ge 1. \end{cases}$$

[6] An equation $\frac{dy}{dt} = f(y)$ has the following phase portrait.



- (a) Find all equilibrium solutions.
- (b) Determine whether each of the equilibrium solutions is stable, asymptotically stable or unstable.
- (c) Graph the solutions y(t) vs t, for the initial values y(1.4) = 0, y(0) = 0.5, y(0) = 1, y(0) = 1.1, y(0) = 1.5, y(-0.5) = 1.5, y(0) = 2, y(0) = 2.5, y(0) = 3, y(0) = 3.5, y(0) = 4, y(0) = 4.5, y(-1) = 4.5. (Without further quantitative information about the equation and the solution formula, it's clearly impossible to draw accurate graphs of y(t) vs t. Here, try to sketch graphs qualitatively to show the correct dynamic properties. The point is that a great deal of info about solution dynamics can be read off from one simple figure of phase portrait.)

[7] Several solution graphs y(t) vs t are given below, for an equation $\frac{dy}{dt} = f(y)$.

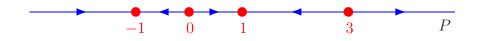


- (a) Find all equilibrium solutions in the interval -4 < y < 4;
- (b) Determine whether each of the above equilibrium solutions is stable, asymptotically stable or unstable;
- (c) Sketch phase portrait on the interval -4 < y < 4.

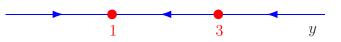
(See next page for answers)

Answers:

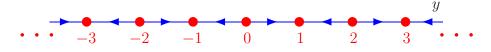
[1] There are four equilibrium solutions: P = -1, 0, 1, 3. The equilibria P = -1 and P = 1 are asymptotically stable. The equilibria P = 0 and P = 3 are unstable.



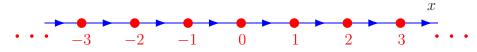
[2] There are two equilibrium solutions: y = 1, 3. The equilibrium y = 1 is asymptotically stable. The equilibrium y = 3 is unstable.



[3] There are infinitely many equilibrium solutions: any integer is an equilibrium. Among these equilibria, odd integers $y = \pm 1, \pm 3, \pm 5, \cdots$ are asymptotically stable, while even integers $y = 0, \pm 2, \pm 4, \pm 6, \cdots$ are unstable.



[4] There are infinitely many equilibrium solutions: any integer is an equilibrium. All equilibria are unstable.

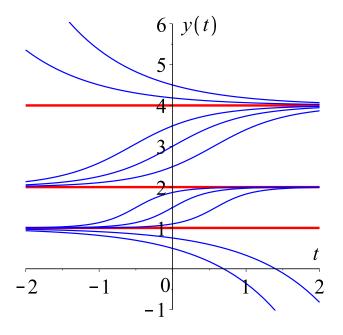


[5] There are infinitely many (actually a continuum of) equilibrium solutions: each point y in the closed interval $0 \le y \le 1$ is an equilibrium. The equilibrium y = 0 is unstable. All other equilibria $0 < y \le 1$ are stable but not asymptotically stable.



[6] There are three equilibria: y = 1, 2, 4. The equilibrium y = 4 is asymptotically stable. The equilibria y = 1 and y = 2 are unstable.

A rough sketch of the solution graphs is given below.



Besides the monotone properties and dynamic behavior of the solutions, also note that the solution graphs between 2 < y < 4 should be all congruent. Indeed, they are horizontal translations of each other. This also holds for each of the following intervals: 1 < y < 2, $4 < y < \infty$, and $-\infty < y < 1$.

[7] There are three equilibria: y = -2, 0, 2. The equilibria y = -2 and y = 2 are asymptotically stable. The equilibrium y = 0 is unstable.

